



Axial Piston Pumps

Series PVplus – Design Series 47 Variable Displacement



ENGINEERING YOUR SUCCESS.

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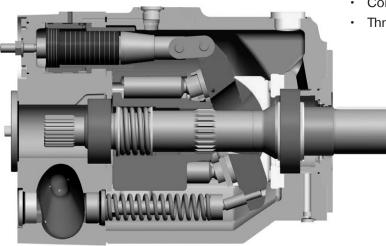
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With through drive for single and multiple pumps

Swash plate type for open circuit

Technical Features

- Low noise level
- Fast response
- Service-friendly
- High self-priming speed
- Compact design
- Through drive for 100 % nominal torque



General Information

Fluid recommendations

Premium quality hydraulic mineral fluid is recommended, like HLP oils to DIN 51524 (part 2 & 3) or ISO6743/4 (HM & HV). Brugger-value recommended to be 30 N/mm² minimum for general application and 50 N/ mm² for heavily loaded hydraulic equipment and fast cycling machines and/or high dynamic loads, measured in accordance with DIN 51 347-2. See also Document MSG30-3248/UK Parker Hydraulic Fluids.

Viscosity

The normal operating viscosity should range between 16 and 100 mm²/s (cSt). Max. start-up viscosity is 1000 mm^2 /s (cSt).

Filtration

For maximum pump and system component functionality and life, the system should be protected from contamination by effective filtration.

Fluid cleanliness should be in accordance with ISO classification ISO 4406:1999. The quality of filter elements should be in accordance with ISO standards.

General hydraulic systems for satisfactory operation: Class 20/18/15, according to ISO 4406:1999

Recommended cleanliness for maximum component life and functionality: Class 18/16/13, according to ISO 4406:1999

Seals

Checkhydraulic fluid specification for chemical resistance of seal material.

Check temperature range of seal material and compare with max. system and ambient temperature.

N – N	litrile (FKM shaft seal)	-25+ 90 °C
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- V FKM (FKM shaft seal) -25...+115 °C
- W Nitrile (PTFE shaft seal) -30...+ 90 °C
- **Note:** The highest fluid temperature will be at the drain port of the pump, up to 25 °C higher than in the reservoir.

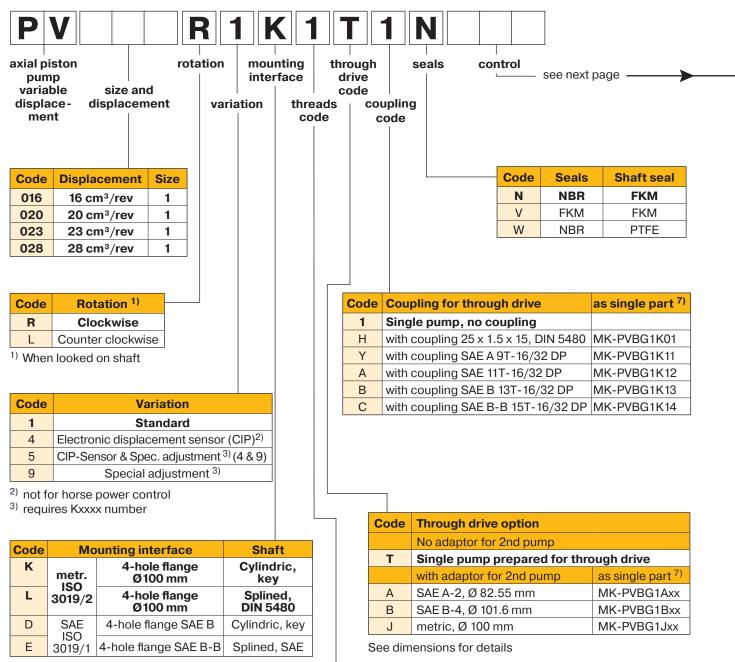


		PV016	PV020	PV023	PV028	PV032	PV040	PV046
Frame size		1	1	1	1	2	2	2
Max. displacement	[cm ³ /rev.]	16	20	23	28	32	40	46
Output flow at 1500 rpm	[l/min]	24	30	34,5	42	48	60	69
Nominal pressure pN	[bar]	350	350	350	350	350	350	350
Min. outlet pressure	[bar]	15	15	15	15	15	15	15
Max. pressure pmax at 20 % working cycle ¹⁾	[bar]	420	420	420	420	420	420	420
Case drain pressure, continuous	[bar]	0.5	0.5	0.5	0.5	0.5	0.5	0.5
Case drain pressure, max. peak	[bar]	2.0	2.0	2.0	2.0	2.0	2.0	2.0
Min. inlet pressure, abs.	[bar]	0.8	0.8	0.8	0.8	0.8	0.8	0.8
Max. inlet pressure	[bar]	16	16	16	16	16	16	16
Input power at 1500 rpm and 350 bar	[kW]	15.9	19.7	22.4	26.9	31.1	38.5	43.8
Max. input torque at 350 bar	[Nm]	94.5	118.1	135.9	165.4	184.3	230.4	265.0
Max speed at 1 bar, abs, inlet pressure	[rpm]	3000	3000	3000	3000	2800	2800	2800
Min. speed	[rpm]	50	50	50	50	50	50	50
Moment of inertia	[kgm ²]	0.0016	0.0016	0.0016	0.0016	0.0047	0.0047	0.0047
Weight	[kg]	19	19	19	19	30	30	30

		PV063	PV080	PV092	PV140	PV180	PV270	PV360
Frame size		3	3	3	4	4	5	6
Max. displacement	[cm ³ /rev.]	63	80	92	140	180	270	360
Output flow at 1500 rpm	[l/min]	94.5	120	138	210	270	405	540
Nominal pressure pN	[bar]	350	350	350	350	350	350	350
Min. outlet pressure	[bar]	15	15	15	15	15	15	15
Max. pressure pmax at 20 % working cycle ¹⁾	[bar]	420	420	420	420	420	420	420
Case drain pressure, continuous	[bar]	0.5	0.5	0.5	0.5	0.5	0.5	0.5
Case drain pressure, max. peak	[bar]	2.0	2.0	2.0	2.0	2.0	2.0	2.0
Min. inlet pressure, abs.	[bar]	0.8	0.8	0.8	0.8	0.8	0.8	0.8
Max. inlet pressure	[bar]	16	16	16	16	16	16	16
Input power at 1500 rpm and 350 bar	[kW]	61.3	76.9	87.5	136.1	173.1	259.6	338.7
Max. input torque at 350 bar	[Nm]	365.2	463.7	533.3	812.4	1044.5	1550.5	2067.4
Max speed at 1 bar, abs, inlet pressure	[rpm]	2800	2500	2300	2400	2200	1800	1750
Min. speed	[rpm]	50	50	50	50	50	50	50
Moment of inertia	[kgm ²]	0.018	0.018	0.018	0.030	0.030	0.098	0.103
Weight	[kg]	59	59	59	90	90	172	180

¹⁾ Check adjustment range each compensator.





⁷⁾ to be ordered separately as single part see page 63.

⁴⁾ Drain, gage and flushing ports

Port⁴⁾

BSPP

UNF

ISO 6149

⁵⁾ All mounting and connecting threads

Threads⁵⁾

metric

UNC

metric

⁶⁾ Mounting interface, code K and L only

Standard pump is not painted. Black painted pump and ATEX (excludes electronic components) certification (Zone 2) is available as special option. For additional informations please contact Parker Hannifin.



Code

1 3

86)

(Cod	е	Control options			
0	0	1	No control			
1	0	0	With cover plate, no control function (fixed displacement pump)			
М	Μ		Standard pressure control			
М	R		Remote pressure control			
Μ	F		Load Sensing (flow) control			
М	Т		Two spool LS control			
			Control variation			
		С	Standard version, integrated pilot valve ¹⁾			
		1	NG6 interface top side for pilot valves ¹⁾			
		2	Remote pressure port int. supply , NG6 interface ²⁾			
		3	Remote pressure port ext. supply ²⁾			
		W	With unloading function, 24VDC solenoid ¹⁾			
		K	Proppilot valve type PVACREK35 mounted			
		Z	Without integrated pilot valve, NG6 interface, for mounting of accessory code PVAC*			
		В	Without integrated pilot valve, without NG6 interface 3)			
		Р	MTZ with mounted pilot valve PVAC1P ²⁾			

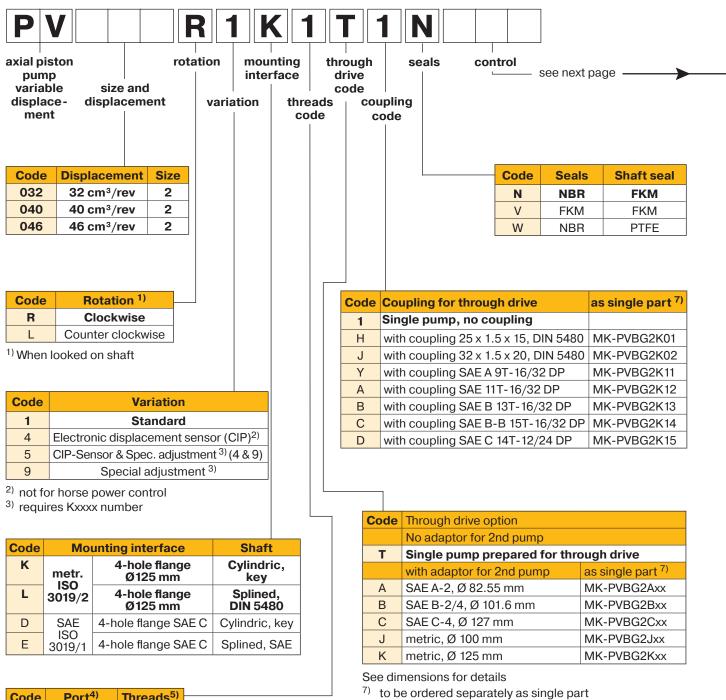
not for MT & *Z
only for MT & *Z
not for MT & MM

			Horse power	/ Torque control			
Code							
			Nominal HP at 1.500 rpm	Nominal torque			
В			3 kW	20 Nm			
С			4 kW	25 Nm			
D			5.5 kW	35 Nm			
Е			7.5 kW	50 Nm			
G			11 kW	71 Nm			
Н			15 kW	97 Nm			
Κ			18.5 kW	120 Nm			
			Fu	nction			
	L		Horse power control with	pressure control ⁴⁾			
	С		Horse power control with	load sensing (single spool)			
	Ζ		Horse power control with	two spool LS control			
			Contro	I variation			
		С	Standard version, integra	ated pilot valve ¹⁾			
		1	NG 6 interface top side				
		W	With unloading function, 24 VDC solenoid				
		Κ	Proppilot valve type PV	ACREK35 mounted			
		Z	Without integrated pilot v for mounting of accessor				
		В	-	alve, without NG6 interface ^{1), 4)}			
		Р	*ZZ with mounted pilot va				

	Code		Control option				
	Electro hydraulic control ⁵⁾						
F	D	V	Proportional displacement control, no pressure compensation				
U	D		Proportional displacement control, with pressure compensation				
			Control variation				
		R	pilot operated pressure control, open NG6 interface				
		к	pilot operated pressure control, proportional pilot valve type PVACREK35 mounted				
		М	pilot operated pressure control, pressure sensor and proportional pilot valve type PVACREK35 mounted for pressure control and/or power control				

⁴⁾ control variation Z and B without pressure pilot

⁵⁾ further info in MSG30-3254



see page 63.

Code	Port ⁴⁾	Threads ⁵⁾	
1	BSPP	metric	
3	UNF	UNC	
8 ⁶⁾	ISO 6149	metric	

⁴⁾ Drain, gage and flushing ports

⁵⁾ All mounting and connecting threads

⁶⁾ Mounting interface, code K and L only

Standard pump is not painted. Black painted pump and ATEX (excludes electronic components) certification (Zone 2) is available as special option. For additional informations please contact Parker Hannifin.



Code		Э	Control options				
0	0	1	No control				
1 0 0 With cover plate, no control function (fixed displacement p							
Μ	М						
Μ	R		Remote pressure control				
M F Load Sensing (flow) control							
MT			Two spool LS control				
			Control variation				
		С	Standard version, integrated pilot valve ¹⁾				
		1	NG6 interface top side for pilot valves ¹⁾				
		2	Remote pressure port int. supply , NG6 interface ²⁾				
		3	Remote pressure port ext. supply ²⁾				
		W	With unloading function, 24VDC solenoid ¹⁾				
		Κ	Proppilot valve type PVACREK35 mounted				
		Ζ	Without integrated pilot valve, NG6 interface,				
for mounting of accessory code PVAC*							
B Without integrated pilot valve, without NG6 interface ³⁾							
P			MTZ with mounted pilot valve PVAC1P ²⁾				

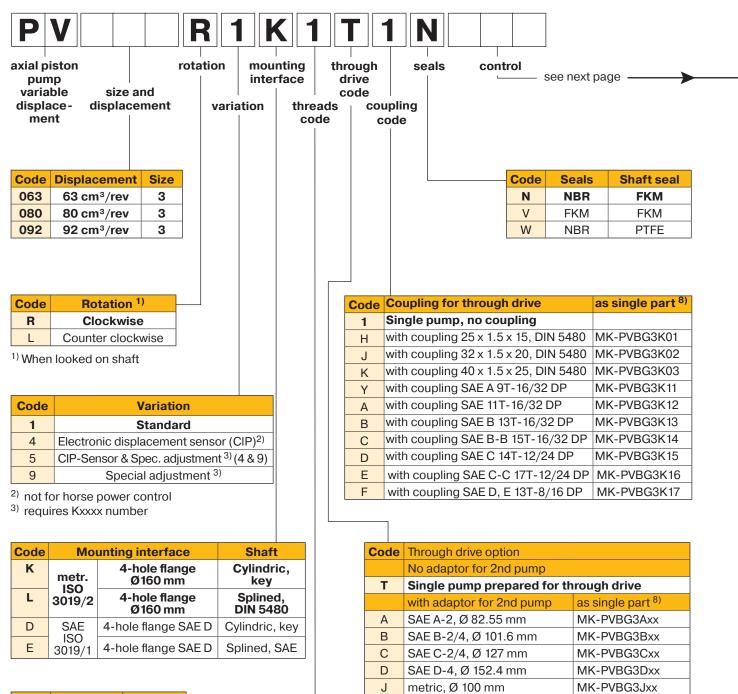
 $^{1)}$ not for MT & *Z $^{2)}$ only for MT & *Z $^{3)}$ not for MT & MM

-	Horse power / Torque control							
C	Code	Э						
			Nominal HP at 1.500 rpm	Nominal torque				
D			5.5 kW	35 Nm				
Е			7.5 kW	50 Nm				
G			11 kW	71 Nm				
Н			15 kW	97 Nm				
Κ			18.5 kW	120 Nm				
М			22 kW	142 Nm				
S			30 kW	195 Nm				
			Fund	ction				
	L		Horse power control with	pressure control ⁴⁾				
	С		Horse power control with	load sensing (single spool)				
	Ζ		Horse power control with	two spool LS control				
			Control	variation				
		С	Standard version, integrat	ted pilot valve ¹⁾				
		1	NG 6 interface top side					
		W	With unloading function, 2	24 VDC solenoid				
		Κ	Proppilot valve type PVA	CREK35 mounted				
		Z		ithout integrated pilot valve, NG6 interface, r mounting of accessory code PVAC* ⁴⁾				
		В	Without integrated pilot va	alve, without NG6 interface ^{1), 4)}				
		Ρ	*ZZ with mounted pilot val	ve PVAC1P ²⁾				

-	Code		Control option				
	Electro hydraulic control ⁵⁾						
F	D	V	Proportional displacement control, no pressure compensation				
U	D		Proportional displacement control, with pressure compensation				
			Control variation				
		R	pilot operated pressure control, open NG6 interface				
		К	pilot operated pressure control, proportional pilot valve type PVACREK35 mounted				
		М	pilot operated pressure control, pressure sensor and proportional pilot valve type PVACREK35 mounted for pressure control and/or power control				

⁴⁾ control variation Z and B without pressure pilot

⁵⁾ further info in MSG30-3254



Code	Port ⁴⁾	Threads ⁵⁾	-
1	BSPP	metric	
3	UNF	UNC	
4 ⁶⁾	BSPP	metr. M14	
87)	ISO 6149	metric	

See dimensions for details

metric, Ø 125 mm

metric, Ø 160 mm

Κ

L.

⁸⁾ to be ordered separately as single part see page 63.

⁴⁾ Drain, gage and flushing ports

⁵⁾ All mounting and connecting threads

- ⁶⁾ For PV063-PV092 only: pressure port 1 1/4" with 4 x M14 instead of 4 x M12
- ⁷⁾ for mounting interface K and L only

Standard pump is not painted. Black painted pump and ATEX (excludes electronic components) certification (Zone 2) is available as special option. For additional informations please contact Parker Hannifin.



MK-PVBG3Kxx

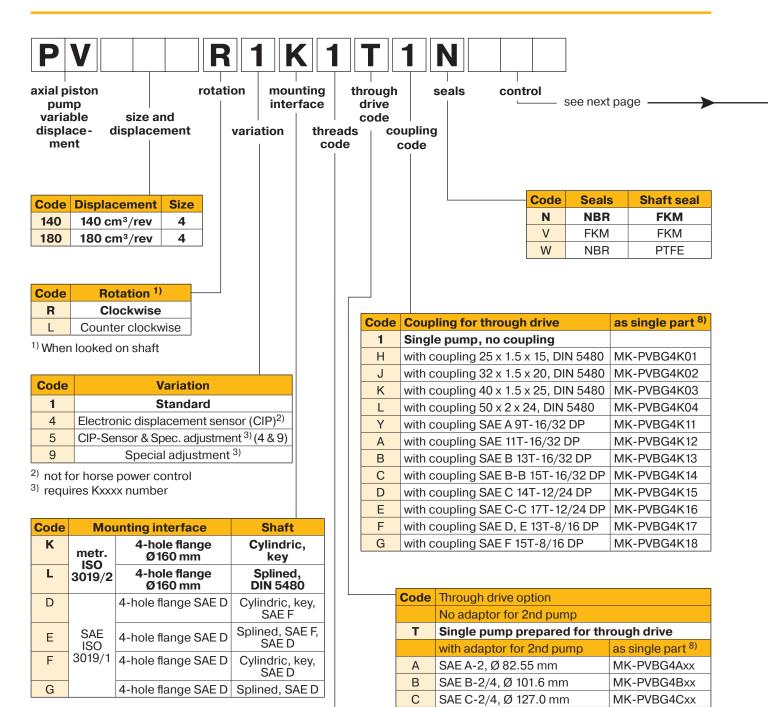
MK-PVBG3Lxx

- C	ode		C	Control options	
0	0	1	No control	•	
1	0	0	With cover plate, no cont	rol function (fixed displacement pump)	
Μ	М		Standard pressure contro	bl	
Μ	R		Remote pressure control		
М	M F Load Sensing (flow) control			rol	
Μ	Т		Two spool LS control		
			C	ontrol variation	
		С	Standard version, integra		
		1	NG6 interface top side fo	r pilot valves ¹⁾	
		2	Remote pressure port int	. supply , NG6 interface ²⁾	
		3	Remote pressure port ex	t. supply ²⁾	
		W	With unloading function,	24VDC solenoid ¹⁾	
		Κ	Proppilot valve type PVA	ACREK35 mounted	
		Z	Without integrated pilot v for mounting of accessor	valve, NG6 interface, ry code PVAC*	
		В		alve, without NG6 interface ³⁾	¹⁾ not for MT & *Z ²⁾ only for MT & *Z
		Р	MTZ with mounted pilot v	alve PVAC1P ²⁾	³⁾ not for MT & MM
			Horse power		
	ode	•	Nominal HP	Newingl	
			at 1.500 rpm	Nominal torque	
G			11 kW	71 Nm	
H			15 kW	97 Nm	
K			18.5 kW	120 Nm	
М			22 kW	142 Nm	
S			30 kW	195 Nm	
Т			37 kW	240 Nm	
U			45 kW	290 Nm	
W			55 kW	355 Nm	
			Fur	nction	
	L		Horse power control with	pressure control ⁴⁾	
	С		Horse power control with	load sensing (single spool)	
	Ζ		Horse power control with	two spool LS control	
			Contro	I variation	
		С	Standard version, integra	ated pilot valve ¹⁾	
		1	NG 6 interface top side		
		W With unloading function, 24 VDC solenoid			
		W	With unloading function,	Proppilot valve type PVACREK35 mounted	
		W K	-		
			Proppilot valve type PVA Without integrated pilot v	ACREK35 mounted alve, NG6 interface,	
		K Z	Proppilot valve type PV Without integrated pilot v for mounting of accessor	ACREK35 mounted alve, NG6 interface, ry code PVAC* ⁴⁾	
		K	Proppilot valve type PV Without integrated pilot v for mounting of accessor	ACREK35 mounted alve, NG6 interface, ry code PVAC ^{* 4)} alve, without NG6 interface ^{1), 4)}	⁴⁾ control variation

- (Code		Control option				
	Electro hydraulic control ⁵⁾						
F	D	V	Proportional displacement control, no pressure compensation				
U	D		Proportional displacement control, with pressure compensation				
	Control variation						
		R	pilot operated pressure control, open NG6 interface				
		к	pilot operated pressure control, proportional pilot valve type PVACREK35 mounted				
		М	pilot operated pressure control, pressure sensor and proportional pilot valve type PVACREK35 mounted for pressure control and/or power control				

control variation Z and B without pressure pilot

⁵⁾ further info in MSG30-3254



D

J

Κ

L

8)

SAE D-4, Ø 152.4 mm

to be ordered separately as single part

metric, Ø 100 mm

metric, Ø 125 mm

metric, Ø 160 mm

See dimensions for details

see page 63.

Code	Port ⁴⁾	Threads ⁵⁾
1	BSPP	metric
3	UNF	UNC
4 ⁶⁾	BSPP	metr. M14
87)	ISO 6149	metric

⁴⁾ Drain, gage and flushing ports

⁵⁾ All mounting and connecting threads

 $^{6)}$ Pressure port 1 1/4" with 4 x M14 instead of 4 x M12

⁷⁾ Mounting interface, code K and L only

Standard pump is not painted. Black painted pump and ATEX (excludes electronic components) certification (Zone 2) is available as special option. For additional informations please contact Parker Hannifin.



MK-PVBG4Dxx

MK-PVBG4Jxx

MK-PVBG4Kxx

MK-PVBG4Lxx

Co	de		Control options	
0	0	1	No control	
1	0	0	With cover plate, no control function (fixed displacement pump)	
М	Μ		Standard pressure control	
Μ	R		Remote pressure control	
Μ	F		Load Sensing (flow) control	
Μ	Т		Two spool LS control	
			Control variation	
		С	Standard version, integrated pilot valve ¹⁾	
		1	NG6 interface top side for pilot valves ¹⁾	
		2	Remote pressure port int. supply , NG6 interface ²⁾	
		3	Remote pressure port ext. supply ²⁾	
		W	With unloading function, 24VDC solenoid ¹⁾	
		Κ	Proppilot valve type PVACREK35 mounted	
		z	Without integrated pilot valve, NG6 interface,	
		2	for mounting of accessory code PVAC*	
		В	Without integrated pilot valve, without NG6 interface ³⁾	
		Ρ	MTZ with mounted pilot valve PVAC1P ²⁾	

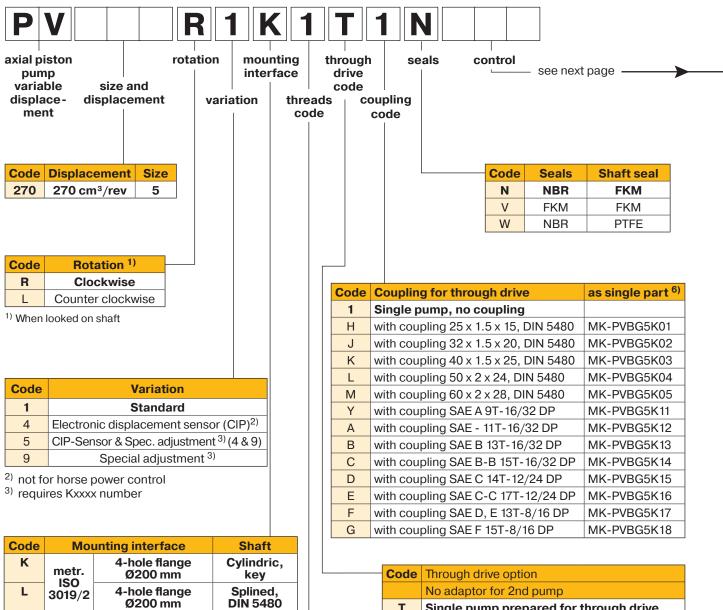
¹⁾ not for MT & *Z ²⁾ only for MT & *Z ³⁾ not for MT & MM

Code				
			Nominal HP	Nominal
			at 1.500 rpm	torque
ĸ			18.5 kW	120 Nm
М			22 kW	142 Nm
S			30 kW	195 Nm
Т			37 kW	240 Nm
U			45 kW	290 Nm
W			55 kW	355 Nm
Y			75 kW	485 Nm
Ζ			90 kW	585 Nm
2			110 kW	700 Nm
3			132 kW	840 Nm
			Fun	ction
	L		Horse power control with	pressure control ⁴⁾
	С		Horse power control with	load sensing (single spool)
	Ζ		Horse power control with	two spool LS control
			Control	variation
		С	Standard version, integra	ted pilot valve ¹⁾
		1	NG 6 interface top side	
		W	With unloading function, 2	24 VDC solenoid
		Κ	Proppilot valve type PVA	CREK35 mounted
		7	Without integrated pilot va	
		2	for mounting of accessory	
		В		alve, without NG6 interface ^{1), 4)}
		Ρ	*ZZ with mounted pilot va	lve PVAC1P ²

⁴⁾ control variation Z and B without pressure pilot

	Code		Control option						
	Electro hydraulic control ⁵⁾								
F	D	V	Proportional displacement control, no pressure compensation						
U	D		Proportional displacement control, with pressure compensation						
	Control variation								
		R	pilot operated pressure control, open NG6 interface						
		к	pilot operated pressure control, proportional pilot valve type PVACREK35 mounted						
pilot operated pressure control, pressure sensor and proportional pilot valve type PVACREK35 mounted for pressure control and/or power control									

⁵⁾ further info in MSG30-3254



oouc	initia and option	
	No adaptor for 2nd pump	
т	Single pump prepared for	through drive
	with adaptor for 2nd pump	as single part ⁶⁾
А	SAE A-2, Ø 82.55 mm	MK-PVBG5Axx
В	SAE B-2/4, Ø 101.6 mm	MK-PVBG5Bxx
С	SAE C-2/4, Ø 127 mm	MK-PVBG5Cxx
D	SAE D-4, Ø 152.4 mm	MK-PVBG5Dxx
Е	SAE E-4, Ø 165.1 mm	MK-PVBG5Exx
J	metric, Ø 100 mm	MK-PVBG5Jxx
К	metric, Ø 125 mm	MK-PVBG5Kxx
L	metric, Ø 160 mm	MK-PVBG5Lxx
М	metric, Ø 200 mm	MK-PVBG5Mxx

See dimensions for details

⁶⁾ to be ordered separately as single part see page 63.

Standard pump is not painted. Black painted pump and ATEX (excludes electronic components) certification (Zone 2) is available as special option. For additional informations please contact Parker Hannifin.



D

Е

Code

1

3

8

SAE

ISO

3019/1

Port⁴⁾

BSPP

UNF

ISO 6149

4) Drain, gage and flushing ports

⁵⁾ All mounting and connecting threads

4-hole flange SAE E

4-hole flange SAE E

Threads⁵⁾

metric

UNC

metric

Cylindric, key

Splined, SAE

(Cod	е	Control options
0	0	1	No control
1	0	0	With cover plate, no control function (fixed displacement pump)
Μ	Μ		Standard pressure control
Μ	R		Remote pressure control
Μ	F		Load Sensing (flow) control
Μ	Т		Two spool LS control
			Control variation
		С	Standard version, integrated pilot valve ¹⁾
		1	NG6 interface top side for pilot valves ¹⁾
		2	Remote pressure port int. supply , NG6 interface ²⁾
		3	Remote pressure port ext. supply ²⁾
		W	With unloading function, 24VDC solenoid ¹⁾
		Κ	Proppilot valve type PVACREK35 mounted
		Z	Without integrated pilot valve, NG6 interface, for mounting of accessory code PVAC*
		В	Without integrated pilot valve, without NG6 interface 3)
		Ρ	MTZ with mounted pilot valve PVAC1P ²⁾

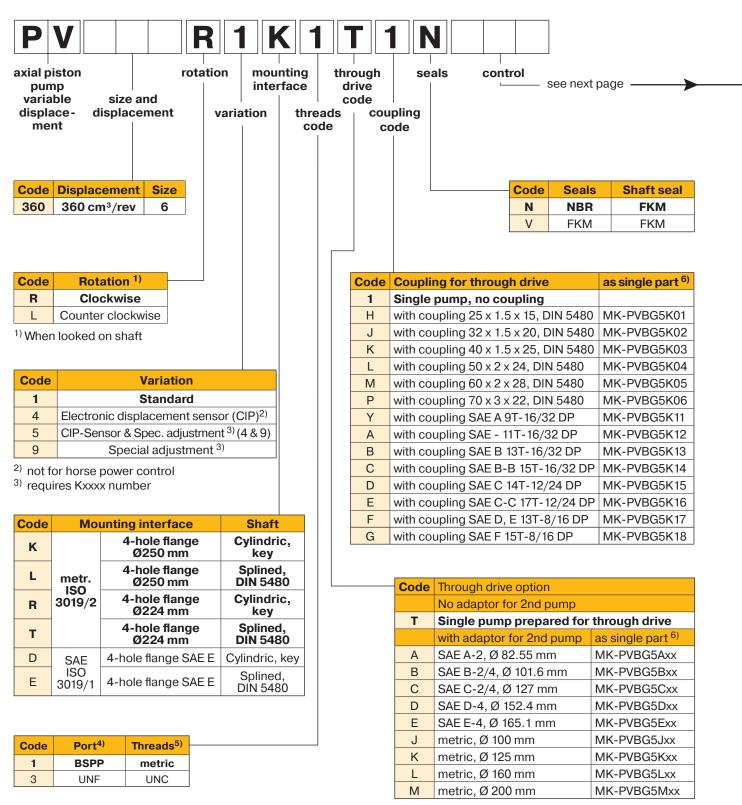
¹⁾ not for MT & *Z ²⁾ only for MT & *Z ³⁾ not for MT & MM

Horse power / Torque control						
Code		Э				
			Nominal HP at 1.500 rpm	Nominal torque		
Т			37 kW	240 Nm		
U			45 kW	290 Nm		
W			55 kW	350 Nm		
Υ			75 kW	480 Nm		
Ζ			90 kW	580 Nm		
2			110 kW	700 Nm		
3			132 kW	840 Nm		
4			160 kW	1020 Nm		
5			180 kW	1150 Nm		
6			200 kW	1280 Nm		
			Fun	ction		
	L		Horse power control with	oressure control ⁴⁾		
	С		Horse power control with I	oad sensing (single spool)		
	Ζ		Horse power control with t	two spool LS control		
			Control	variation		
		С	Standard version, integrat	ed pilot valve ¹⁾		
		1	NG 6 interface top side			
		W	With unloading function, 2	4 VDC solenoid		
		Κ	Proppilot valve type PVA	CREK35 mounted		
		Z	Without integrated pilot va for mounting of accessory	lve, NG6 interface, / code PVAC* ⁴⁾		
		В	Without integrated pilot va	lve, without NG6 interface ^{1), 4)}		
		Р	*ZZ with mounted pilot val			

⁴⁾ control variation Z and B without pressure pilot

- (Code		Control option						
	Electro hydraulic control ⁵⁾								
F	D	V	Proportional displacement control, no pressure compensation						
U	D		Proportional displacement control, with pressure compensation						
	Control variation								
		R	pilot operated pressure control, open NG6 interface						
		ĸ	pilot operated pressure control, proportional pilot valve type PVACREK35 mounted						
		M	pilot operated pressure control, pressure sensor and proportional pilot valve type PVACREK35 mounted for pressure control and/or power control						

⁵⁾ further info in MSG30-3254



See dimensions for details

⁶⁾ to be ordered separately as single part see page 63.

Standard pump is not painted. Black painted pump and ATEX (excludes electronic components) certification (Zone 2) is available as special option. For additional informations please contact Parker Hannifin.



⁴⁾ Drain, gage and flushing ports

⁵⁾ All mounting and connecting threads

- (Code	е	Control options
0	0	1	No control
1	0	0	With cover plate, no control function (fixed displacement pump)
Μ	Μ		Standard pressure control
Μ	R		Remote pressure control
Μ	F		Load Sensing (flow) control
Μ	Т		Two spool LS control
			Control variation
		С	Standard version, integrated pilot valve ¹⁾
		2	Remote pressure port int. supply , NG6 interface ²⁾
		3	Remote pressure port ext. supply ²⁾
		W	With unloading function, 24VDC solenoid ¹⁾
		K	Proppilot valve type PVACREK35 mounted
		Z	Without integrated pilot valve, NG6 interface, for mounting of accessory code PVAC*
		В	Without integrated pilot valve, without NG6 interface 3)
		Р	MTZ with mounted pilot valve PVAC1P ²⁾

¹⁾ not for MT & *Z ²⁾ only for MT & *Z ³⁾ not for MT & MM

Horse power / Torque control					
C	Cod	е			
			Nominal HP at 1.500 rpm	Nominal torque	
U			45 kW	290 Nm	
W			55 kW	350 Nm	
Υ			75 kW	480 Nm	
Ζ			90 kW	580 Nm	
2			110 kW	700 Nm	
3			132 kW	840 Nm	
4			160 kW	1020 Nm	
5			180 kW	1150 Nm	
6			200 kW	1280 Nm	
			F	Function	
	L		Horse power control w	ith pressure control ⁴⁾	
	С		Horse power control w	ith load sensing (single spool)	
	Ζ		Horse power control w	ith two spool LS control	
			Cont	rol variation	
		С	Standard version, inte	grated pilot valve ¹⁾	
		1	NG 6 interface top side	9	
		W	With unloading functio	n, 24 VDC solenoid	
		Κ	Proppilot valve type F	PVACREK35 mounted	
		Z	Without integrated pilo for mounting of access	ot valve, NG6 interface, sory code PVAC ^{* 4)}	
		В	Without integrated pilo	t valve, without NG6 interface ^{1), 4)}	
		Р	*ZZ with mounted pilot	t valve PVAC1P ²	

Remark:

As torque is pretty much speed independent power at alternative speeds can get recalculated to 1500 rpm for code selection easily.

Example:

Your engine allows 90 kW @ 1800 rpm → <u>90 kW</u> x 1500 rpm = 75 kW

→ select a first digit "Y"-control.

⁴⁾ control variation Z and B without pressure pilot

⁵⁾ further info in MSG30-3254

	Code		Control option					
	Electro hydraulic control ⁵⁾							
F	D	V	Proportional displacement control, no pressure compensation					
U	D		Proportional displacement control, with pressure compensation					
	Control variation							
		R	pilot operated pressure control, open NG6 interface					
		к	pilot operated pressure control, proportional pilot valve type PVACREK35 mounted					
		М	pilot operated pressure control, pressure sensor and proportional pilot valve type PVACREK35 mounted for pressure control and/or power control					

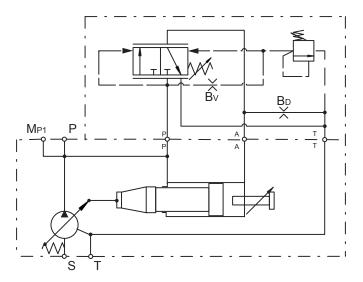


Standard Pressure Control

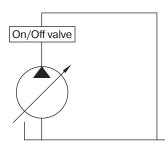
Control option MMC

The standard pressure control adjusts the pump displacement according to the actual need of flow in the system in order to keep the pressure constant.

Control schematics



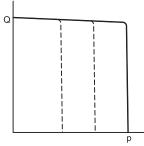
Response times of the pump are collected from a circuit as below by measuring the pumps swash angle movement at different pressures.



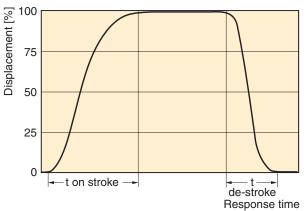
	Time on-stroke [ms]		Time de-s	troke [ms]
	against 50 bar	against 350 bar	zero stroke 50 bar	zero stroke 350 bar
PV360	520	180	120	82

Pressure adjustment range	15 to 420 bar
Factory setting pressure	50 bar
Differential pressure adjustment range	10 to 40 bar
Factory setting differential pressure	15 bar
Control oil consumption	Max 8.0 I/min
Typical pilot flow	approx 1.5 l/min

Note: Upgrade to the MRC control by simply removing the ISO 6149 M14x1.5-plug. Thread adapters PVCCK** (last two digits defining seal and thread) are available separately if required. PVCCKN1 for ex. for NBR-sealed and towards G1/4 BSPP. Please consult spares list for all further versions.



Dynamic characteristic of flow control *



* Curve shown exaggerated



Standard Pressure Control with NG6 Interface

Control option MM1

With code MM1 the standard pressure control has a valve interface size NG 6 DIN 24340 (CETOP 03 acc. RP35H, NFPA D03) on the top side.

This interface allows the mounting of accessories like multiple pressure selectors without the need of external piping and valve mounting.

Standard Pressure Control with Electrical Unloading

Control option MMW

With code MMW a solenoid operated directional control valve (D1VW002KNJW) for electrical unloading is mounted on the control top side.

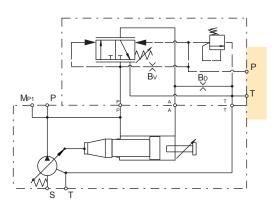
When the solenoid is de-energised, the pump compensates at a stand-by pressure of typically 15 bar. When the solenoid is energised, the pump compensates at the pressure adjusted on the integrated pilot valve.

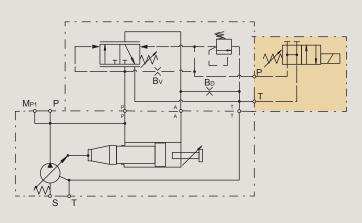
Standard Pressure Control with Proportional Pilot Valve

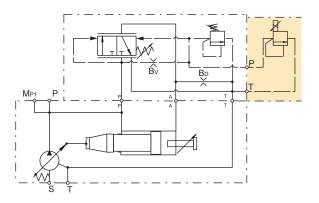
Control option MMK

With code MMK a proportional pilot valve of type PVACRE... K35 (see page 43) is mounted on the top side interface.

This allows a variation of the pump compensating pressure between 20 and 350 bar by an electrical signal.







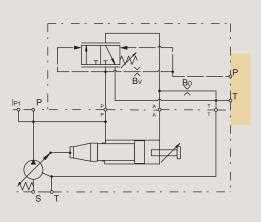
Standard Pressure Control without Integrated Pressure Pilot Valve

Control option MMZ

Control MMZ has no integrated pilot valve but a valve interface NG6 DIN 24340 on the top.

This version is recommended for valve accessories.

For operation at >350 bar please select respective valve accessories (see page 40)



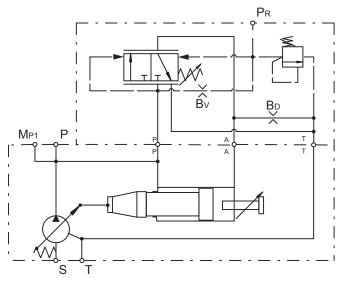


Remote Pressure Control

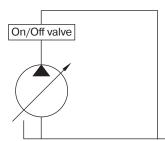
Control option MRC

The remote pressure control adjusts the pump displacement according to the actual need of flow in the system

Control schematics



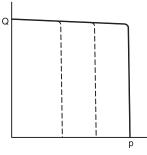
Response times of the pump are collected from a circuit as below by measuring the pumps swash angle movement at different pressures.



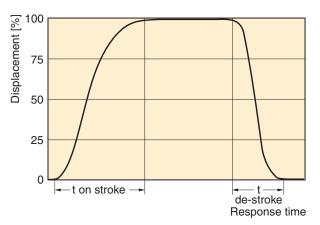
	Time on-stroke [ms]		Time de-s	troke [ms]
	against 50 bar	against 350 bar	zero stroke 50 bar	zero stroke 350 bar
PV360	520	180	120	82

Pressure adjustment range	15 to 420 bar
Factory setting pressure	50 bar
Differential pressure adjustment range	10 to 40 bar
Factory setting differential pressure	15 bar
Control oil consumption	Max 8.0 I/min
Typical pilot flow	approx 1.5 l/min

in order to keep the pressure constant at a level given by a remotely installed pilot valve.



Dynamic characteristic of flow control *



* Curve shown exaggerated



Remote Pressure Control with NG6 Interface

Control option MR1

With code MR1 the remote pressure control has a valve interface size NG 6 DIN 24340 (CETOP 03 acc. RP35H, NFPA D03) on the top side.

This interface allows the mounting of accessories like multiple pressure selectors without the need of external piping and valve mounting.

Remote Pressure Control with Electrical Unloading

Control option MRW

With code MRW a solenoid operated directional control valve (D1VW002KNJW) for electrical unloading is mounted on the control top side.

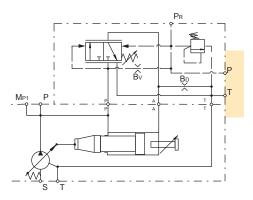
When the solenoid is de-energised, the pump compensates at a stand-by pressure of typically 15 bar. When the solenoid is energised, the pump compensates at the pressure adjusted on the integrated pilot valve.

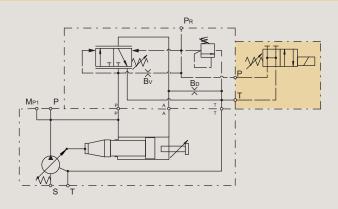
Remote Pressure Control with Proportional Pilot Valve

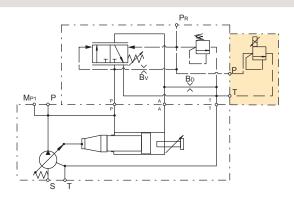
Control option MRK

With code MRK a proportional pilot valve of type PVACRE...K35 (see page 43) is mounted on the top side interface.

This allows a variation of the pump compensating pressure between 20 and 350 bar by an electrical signal.



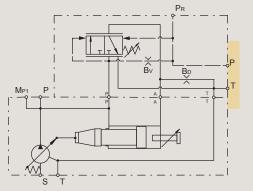




Remote Pressure Control without Integrated Pressure Pilot Valve

Control option MRZ

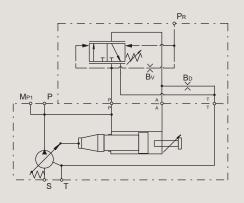
Control MRZ has no integrated pilot valve but a NG6 DIN 24340 interface topside.



This version is recommended for valve accessories.

Control option MRB

Control MRB has no integrated pilot valve.

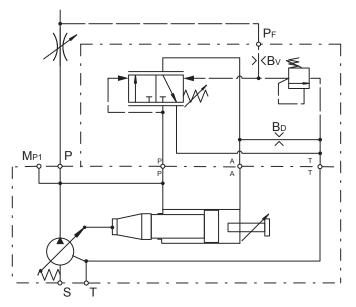


Load Sensing Control

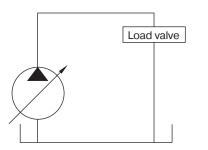
Control option MFC

The pilot pressure of the load sensing control is taken from a load sensing port in the hydraulic system. It is

Control schematics



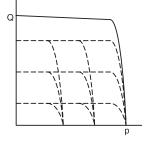
Response times of the pump are collected from a circuit as below by measuring the pumps swash angle movement at different pressures.



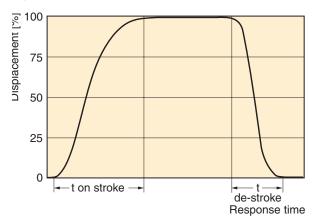
	Time on-stroke [ms]		Time de-s	troke [ms]
	stand-by to 50 bar	stand-by to 350 bar	50 bar to stand-by	350 bar to stand-by
PV360	500	690	830	50

Pressure adjustment range	15 to 420 bar
Factory setting pressure	50 bar
Differential pressure adjustment range	10 to 40 bar
Factory setting differential pressure	10 bar
Control oil consumption	Max 8.0 I/min
Typical pilot flow	approx 1.5 l/min

used to match pump flow to system demands. Integrated pilot valve allows pmax adjustment.



Dynamic characteristic of flow control *



* Curve shown exaggerated



Load Sensing Control with NG6 Interface

Control option MF1

With code MF1 the remote pressure control has a valve interface size NG 6 DIN 24340 (CETOP 03 acc. RP35H, NFPA D03) on the top side.

This interface allows the mounting of accessories like multiple pressure selectors without the need of external piping and valve mounting.

Load Sensing Control with Electrical Unloading

Control option MFW

With code MFW a solenoid operated directional control valve (D1VW002KNJW) for electrical unloading is mounted on the control top side.

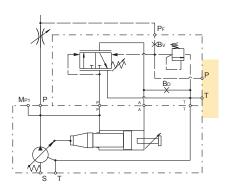
When the solenoid is de-energised, the pump compensates at a stand-by pressure of typically 15 bar. When the solenoid is energised, the pump compensates at the pressure adjusted on the integrated pilot valve.

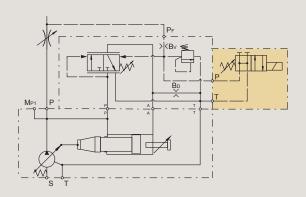
Load Sensing Control with Proportional Pilot Valve

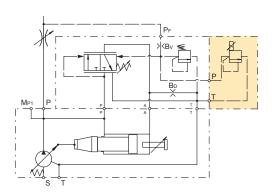
Control option MFK

With code MFK a proportional pilot valve of type PVACRE...K35 (see page 43) is mounted on the top side interface.

This allows a variation of the pump compensating pressure between 20 and 350 bar by an electrical signal.







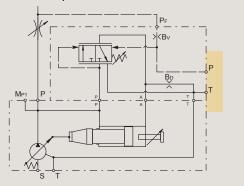
Load Sensing Control without Integrated Pressure Pilot Valve

Control option MFZ

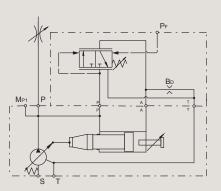
24340 interface topside.

Control option MFB

Control MFZ has no integrated pilot valve but a NG6 DIN Control MFB has no integrated pilot valve.



This version is recommended for valve accessories.



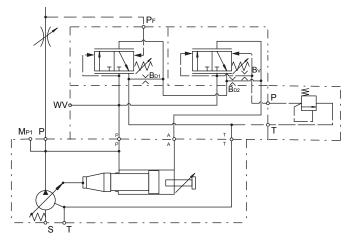


2 Spool Load Sensing Control

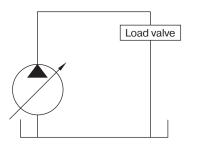
Control option MTP

The pilot pressure of the load sensing control is taken from a load sensing port in the hydraulic system. It is used to match pump flow to system demands. With the 2

Control schematics

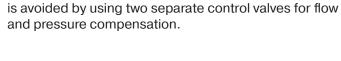


Response times of the pump are collected from a circuit as below by measuring the pumps swash angle movement at different pressures.

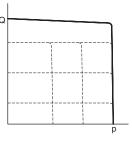


	Time on-stroke [ms]		Time de-s	troke [ms]
	stand-by to 50 bar	stand-by to 350 bar	50 bar to stand-by	350 bar to stand-by
PV360	920	670	1000	170

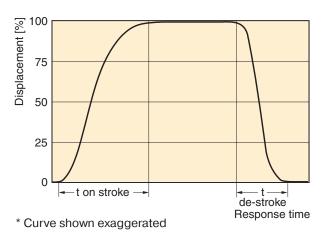
Pressure adjustment range	15 to 420 bar
Factory setting pressure	50 bar
Differential pressure adjustment range	10 to 40 bar
Factory setting differential pressure load sensing	10 bar
Factory setting differential pressure, pressure control	15 bar
Control oil consumption	Max 8.0 I/min
Typical pilot flow	approx 1.5 l/min



spool control the interaction of the two control functions



Dynamic characteristic of flow control *





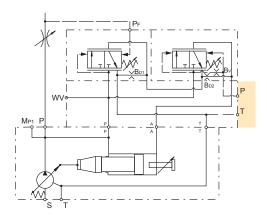
2 Spool Load Sensing Control with NG6 Interface without Integrated Pressure Pilot Valve

Control option MTZ

Control MTZ has no integrated pressure pilot valve but NG 6 DIN 24340 (CETOP 03 acc. RP35H, NFPA D03) on the top side.

This interface allows the mounting of accessories like multiple pressure selectors without the need of external piping and valve mounting.

Note: The MT1 control option is not available for new releases as is it identical to the MTZ control.



2 Spool Load Sensing Control with Proportional Pilot Valve

Control option MTK

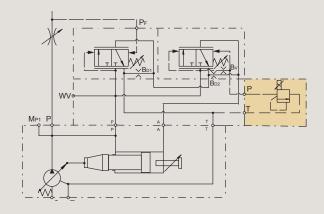
With code MTK a proportional pilot valve of type PVACRE...K35 (see page 43) is mounted on the top side interface.

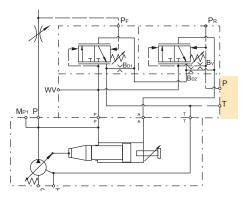
This allows a variation of the pump compensating pressure between 20 and 350 bar by an electrical signal.

2 Spool Load Sensing Control without Integrated Pressure Pilot Valve

Control option MT2

Control MT2 has a valve interface NG6 DIN 24340 on the top side and remote pressure port internal supply.

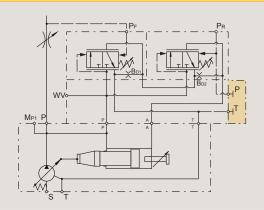




2 Spool Load Sensing Control without Integrated Pressure Pilot Valve

Control option MT3

Control MT3 with pressure remote port external supply. Incl. closed NG6-pad.



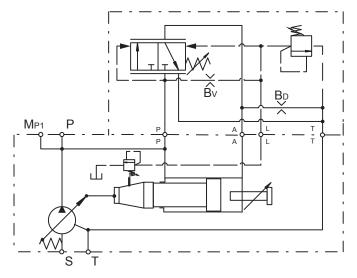


Horse Power/Torque Controls with Pressure Control

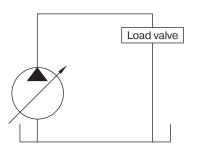
Control option *LC

The horse power control type L^* provides the benefit of the pressure control, plus the ability to limit the input power the pump will draw. These controls are beneficial when the power available from the prime mover for the hydraulics is limited or the application power demand has both high flow/low pressure and low flow/high pressure duty cycles.

Control schematics



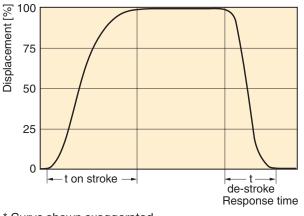
Response times of the pump are collected from a circuit as below by measuring the pumps swash angle movement at different pressures.



	Time on-stroke [ms]		Time de-s	troke [ms]
	against 50 bar	against 350 bar	zero stroke 50 bar	zero stroke 350 bar
PV360	90	90	100	100

Pressure adjustment range	15 to 350 bar
Factory setting pressure	350 bar
Differential pressure adjustment range	10 to 40 bar
Factory setting differential pressure	15 bar
Control oil consumption	Max 8.0 I/min
Typical pilot flow	approx 1.5 l/min

Dynamic characteristic of flow control *



* Curve shown exaggerated

See Horse Power characteristic curves on page 30



Horse Power/Torque Control with NG6 Interface

Control option *L1

With code *L1 the horse power control has a valve interface size NG 6 DIN 24340 (CETOP 03 acc. RP35H, NFPA D03) on the top side.

This interface allows the mounting of accessories like multiple pressure selectors without the need of external piping and valve mounting.

Horse Power/Torque Control with Electrical Unloading

Control option *LW

With code *LW a solenoid operated directional control valve (D1VW002KNJW) for electrical unloading is mounted on the control top side.

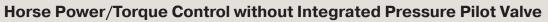
When the solenoid is de-energised, the pump compensates at a stand-by pressure of typically 15 bar. When the solenoid is energised, the pump compensates at the pressure adjusted on the integrated pilot valve.

Horse Power/Torque Control with Proportional Pilot Valve

Control option *LK

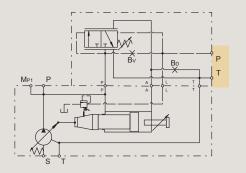
With code *LK a proportional pilot valve of type PVACRE... K35 (see page 43) is mounted on the top side interface.

This allows a variation of the pump compensating pressure between 20 and 350 bar by an electrical signal.



Control option *LZ

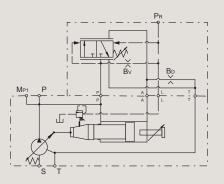
Control *LZ has no integrated pilot valve but a NG6 DIN 24340 interface topside.



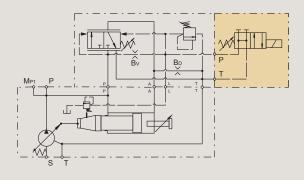
This version is recommended for valve accessories.

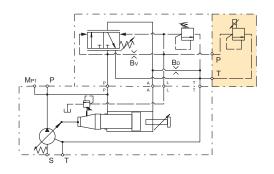
Control option *LB

Control *LB has no integrated pilot valve.









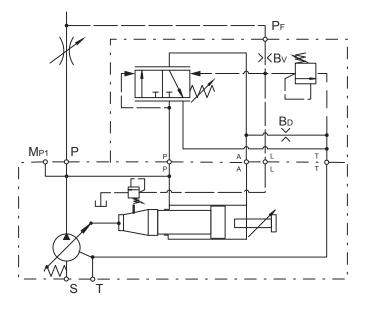
Horse Power/Torque Controls with Load Sensing

Control option *CC

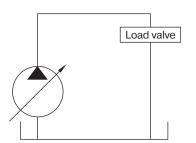
The horse power control type C^* provides the benefit of the load sensing control, plus the ability to limit the input power the pump will draw. These controls are beneficial when the power available from the prime mover for the

hydraulics is limited or the application power demand has both high flow/low pressure and low flow/high pressure duty cycles.

Control schematics



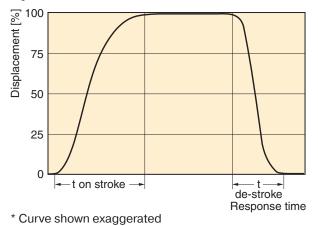
Response times of the pump are collected from a circuit as below by measuring the pumps swash angle movement at different pressures.



	Time on-stroke [ms]		Time de-st	troke [ms]
	stand-by to 50 bar	stand-by to 350 bar	50 bar to stand-by	350 bar to stand-by
PV360	90	90	100	100

Pressure adjustment range	15 to 350 bar
Factory setting pressure	350 bar
Differential pressure adjustment range	10 to 40 bar
Factory setting differential pressure	15 bar
Control oil consumption Max 8.0 l/min	
Typical pilot flow	approx 1.5 l/min

Dynamic characteristic of flow control *



See Horse Power characteristic curves on page 30



Horse Power/Torque Control with Load Sensing & NG6 Interface

Control option *C1

With code *C1 the horse power control has a valve interface size NG 6 DIN 24340 (CETOP 03 acc. RP35H, NFPA D03) on the top side.

This interface allows the mounting of accessories like multiple pressure selectors without the need of external piping and valve mounting.

Horse Power/Torque Control with Load Sensing & Electrical Unloading

Control option *CW

With code *CW a solenoid operated directional control valve (D1VW002KNJW) for electrical unloading is mounted on the control top side.

When the solenoid is de-energised, the pump compensates at a stand-by pressure of typically 15 bar. When the solenoid is energised, the pump compensates at the pressure adjusted on the integrated pilot valve.

Horse Power/Torque Control with Load Sensing & Proportional Valve

Control option *CK

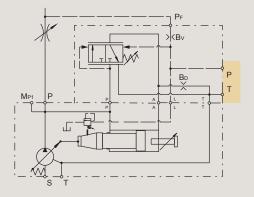
With code *CK a proportional pilot valve of type PVACRE...K35 (see page 43) is mounted on the top side interface.

This allows a variation of the pump compensating pressure between 20 and 350 bar by an electrical signal.

Horse Power/Torque Control with Load Sensing without Integrated Pilot Valve

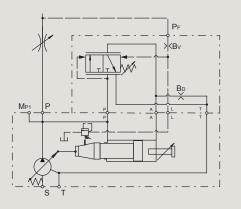
Control option *CZ

Control *CZ has no integrated pilot valve but NG6 DIN 24340 interface topside.

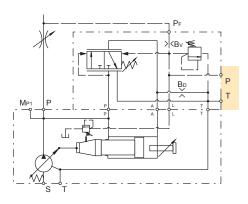


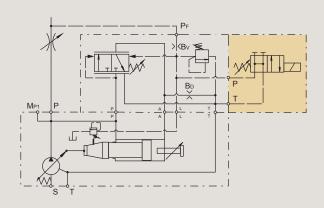
Control option *CB

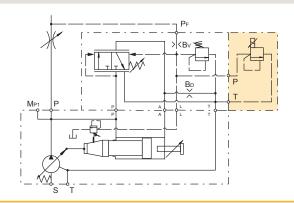
Control *CB has no integrated pilot valve.





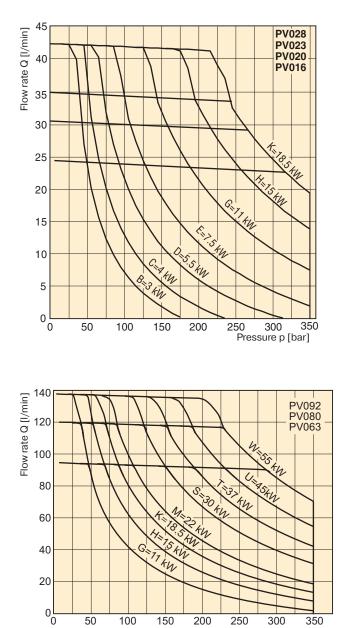


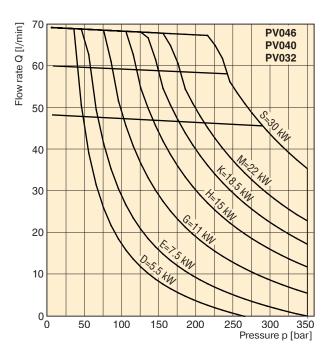




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Typical Horse Power/Torque Control Characteristics

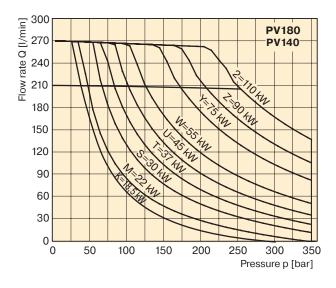


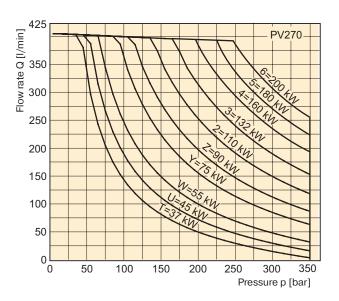


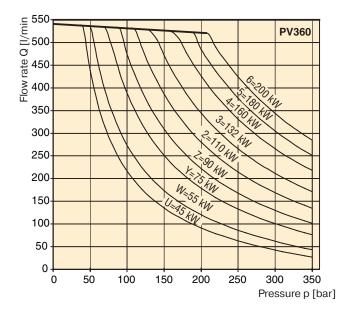


Pressure p [bar]

Typical Horse Power/Torque Control Characteristics







Speed	:	n = 1500 rev/min
Temperature	:	t = 50 °C
Fluid	:	HLP, ISO VG46
Viscosity	:	$v = 46 \text{ mm}^2/\text{s} \text{ at } 40 ^\circ\text{C}$
Pressure	:	Maximum 350 bar, depending on HP level

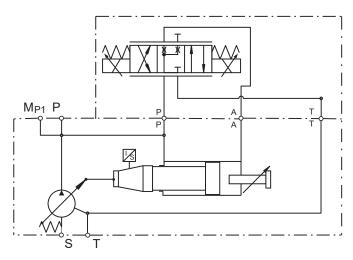


Proportional Displacement Control

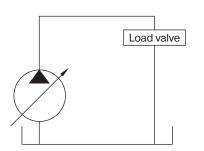
Control option FDV

The proportional displacement control allows the adjustment of the pump's output flow by an electrical input signal. The actual displacement of the pump is monitored by an electronic displacement sensor and compared with the commanded displacement in an electronic control module PQDXXA-Z10. The command is given as an electrical input signal (0 – 10 V alternatively 4 - 20 mA) from the supervising machine control or a potentiometer.

Control schematics



Response times of the pump are collected from a circuit as below by measuring the pumps swash angle movement at different pressures.

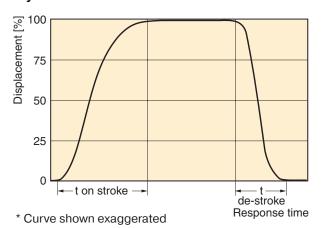


(Time on-s	troke [ms]	Time de-stroke [ms]		
		stand-by to 50 bar	stand-by to 350 bar	50 bar to stand-by	350 bar to stand-by	
	PV360	255	154	266	183	

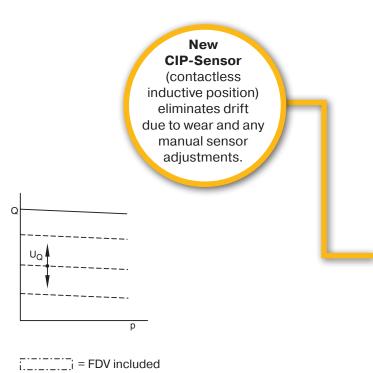
Pressure adjustment range*	35 to 350 bar
Differential pressure adjustment range *	10 to 40 bar
Factory setting differential pressure *	15 bar
Control oil consumption (FDV only)	Max 0.3 I/min

* Data valid for UD* version

Dynamic characteristic of flow control *



Internal pilot pressure required to control the pump		
FDV	15 bar	
UDR	25 bar	
UDK	25 bar	
UDM	25 bar	



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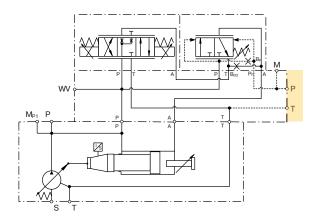


Proportional Displacement Control with Overriding Pressure Control

Control option UDR

Control version UDR provides electro-hydraulic displacement control and pressure stage mounted on an elbow manifold.

The elbow manifold provides NG6/D03 interface on top to mount a pressure pilot valve (not included in UDR).



w

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Mp.

Proportional Displacement Control with Proportional Pressure Control

Control option UDK

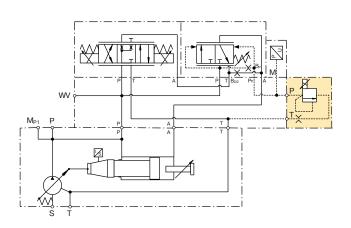
Control version UDK features proportional pressure pilot valve PVACRE...K35, which enables for electro-hydraulic p/Q control.

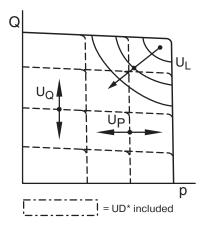
By using the digital module PQDXXA-Z10 it is possible to control the displacement proportionally with overriding open loop proportional pressure control.

Proportional Displacement Control with Closed Loop Pressure Control

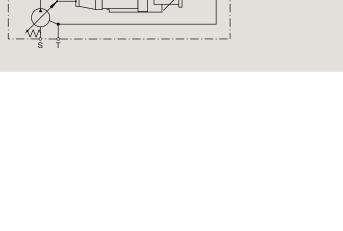
Control option UDM

Control version UDM includes pressure transducer Parker SCP 8181 CE. In combination with control module PQDXXA-Z10 both closed loop pressure control as well as electronic power limitation can be realized.



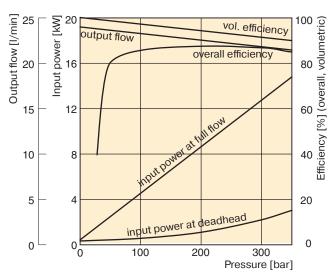




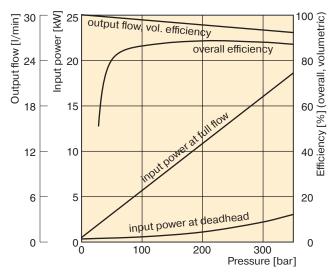


Efficiency, power consumption

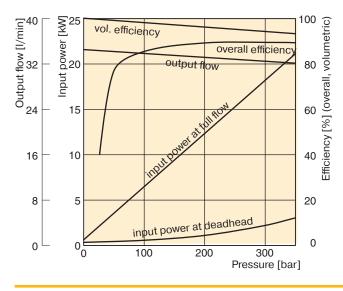












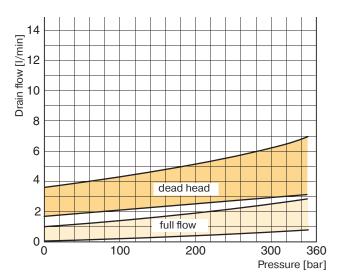
Efficiency and case drain flows PV016, PV020, PV023 and PV028

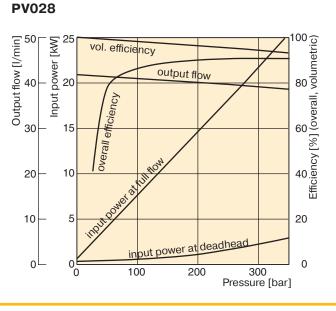
The efficiency and power graphs are measured at an input speed of n = 1500 rpm, a temperature of 50 °C and a fluid viscosity of 30 mm²/s.

Case drain flow and compensator control flow leave via the drain port of the pump. To the values shown are to be added 1 to 1.2 l/min, if at pilot operated compensators the control flow of the pressure pilot valve also goes through the pump.

Please note: The values shown below are only valid for static operation. Under dynamic conditions and at rapid compensation of the pump the volume displaced by the servo piston also leaves the case drain port. This dynamic control flow can reach up to 401/min! Therefore the case drain line is to lead to the reservoir at full size and without restrictions as short and direct as possible.

Case drain flow PV016-028 with pressure compensator



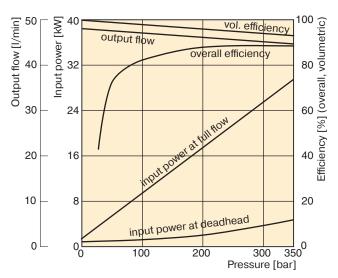


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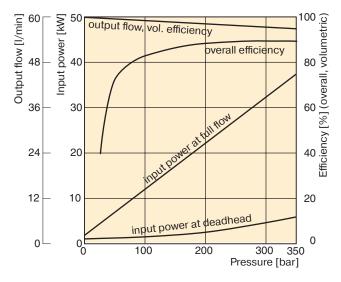
-Parker

Efficiency, power consumption

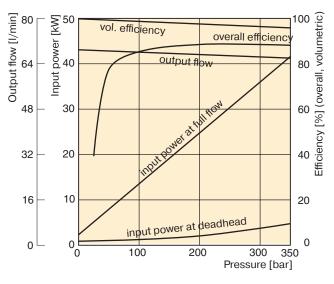
PV032



PV040







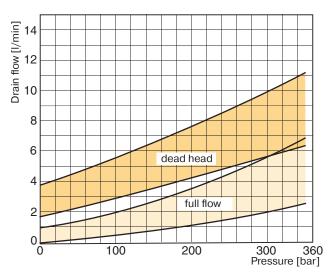
Efficiency and case drain flows PV032 to PV046

The efficiency and power graphs are measured at an input speed of n = 1500 rpm, a temperature of 50 °C and a fluid viscosity of 30 mm²/s.

Case drain flow and compensator control flow leave via the drain port of the pump. To the values shown are to be added 1 to 1.2 l/min, if at pilot operated compensators the control flow of the pressure pilot valve also goes through the pump.

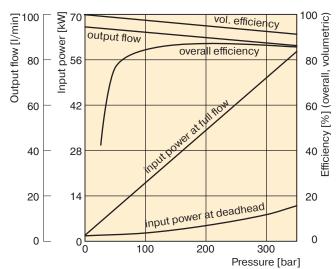
Please note: The values shown below are only valid for static operation. Under dynamic conditions and at rapid compensation of the pump the volume displaced by the servo piston also leaves the case drain port. This dynamic control flow can reach up to 60 l/min! Therefore the case drain line is to lead to the reservoir at full size and without restrictions as short and direct as possible.

Case drain flow PV032-046 with pressure compensator

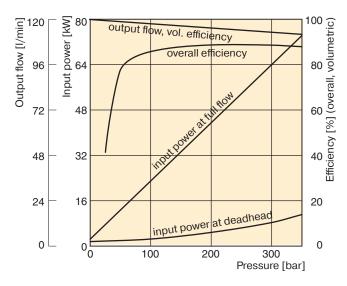


Efficiency, power consumption

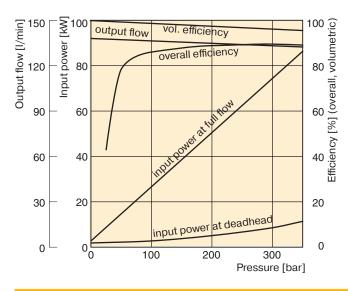
PV063



PV080







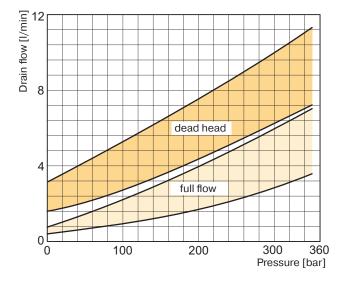
Efficiency and case drain flows PV063, PV080, PV092

The efficiency and power graphs are measured at an input speed of n = 1500 rpm, a temperature of 50 °C and a fluid viscosity of 30 mm²/s.

Case drain flow and compensator control flow leave via the drain port of the pump. To the values shown are to be added 1 to 1.2 l/min, if at pilot operated compensators the control flow of the pressure pilot valve also goes through the pump.

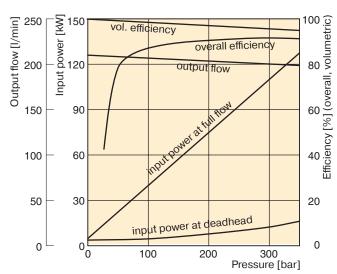
Please note: The values shown below are only valid for static operation. Under dynamic conditions and at rapid compensation of the pump the volume displaced by the servo piston also leaves the case drain port. This dynamic control flow can reach up to 80 l/min! Therefore the case drain line is to lead to the reservoir at full size and without restrictions as short and direct as possible.

Case drain flows PV063-092

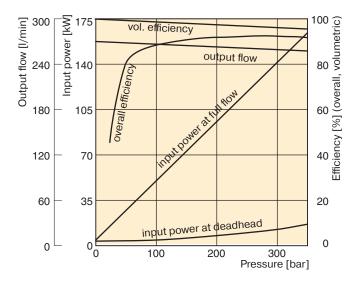


Efficiency, power consumption

PV140



PV180

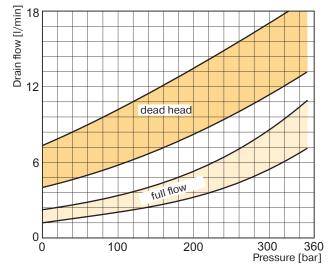


Efficiency and case drain flows PV140, PV180

The efficiency and power graphs are measured at an input speed of n = 1500 rpm, a temperature of 50 °C and a fluid viscosity of 30 mm²/s.

Case drain flow and compensator control flow leave via the drain port of the pump. To the values shown are to be added 1 to 1.2 l/min, if at pilot operated compensators the control flow of the pressure pilot valve also goes through the pump.

Please note: The values shown below are only valid for static operation. Under dynamic conditions and at rapid compensation of the pump the volume displaced by the servo piston also leaves the case drain port. This dynamic control flow can reach up to 120 I/min! Therefore the case drain line is to lead to the reservoir at full size and without restrictions as short and direct as possible.



Case drain flows PV140-180



₹250 vol. efficiency overall efficiency 00 Output flow [I/min] 500 Efficiency [%] (overall, volumetric) ver output flow <u>6</u>200 400 80 Input 300 150 60 200 100 40 100 50 20 input power at deadhead 0 0 0 100 200 300 Pressure [bar]

Efficiency, power consumption PV270

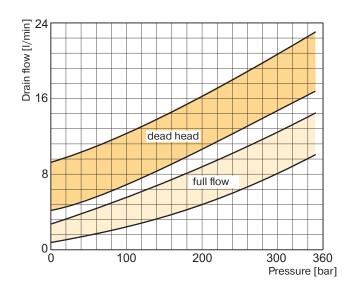
Efficiency and case drain flows PV270

The efficiency and power graphs are measured at an input speed of n = 1500 rpm, a temperature of 50 °C and a fluid viscosity of 30 mm²/s.

Case drain flow and compensator control flow leave via the drain port of the pump. To the values shown are to be added 1 to 1.2 l/min, if at pilot operated compensators the control flow of the pressure pilot valve also goes through the pump.

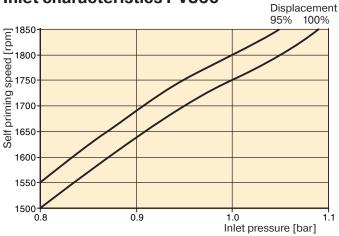
Please note: The values shown below are only valid for static operation. Under dynamic conditions and at rapid compensation of the pump the volume displaced by the servo piston also leaves the case drain port. This dynamic control flow can reach up to 120 l/min! Therefore the case drain line is to lead to the reservoir at full size and without restrictions as short and direct as possible.

Case drain flows PV270

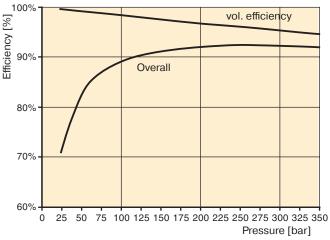




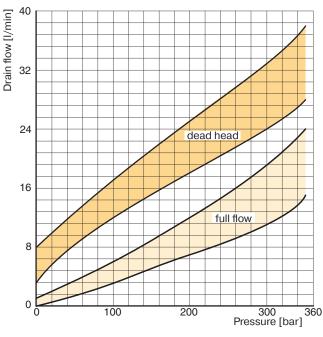
Typical inlet characteristics vs. speed at various percentage displacements Inlet characteristics PV360



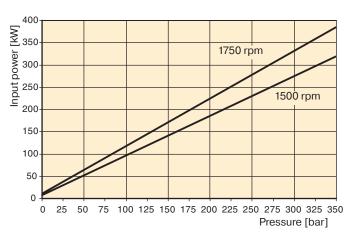
Typical efficiency at full displacement and 1500 rpm PV360



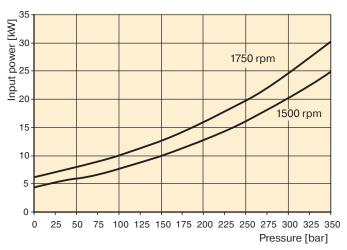
Case drain flows PV360



Typical drive power at full displacement Input power – full stroke PV360

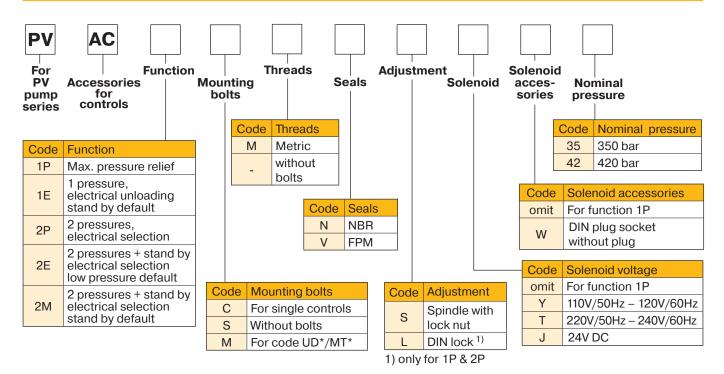


Typical compensated power Input power – zero stroke PV360



The curves show typical characteristics measured under following conditions: Fluid: Mineral oil ISO VG 22 at 32 °C Inlet pressure 1,0 bar (absolute), measured at inlet port.

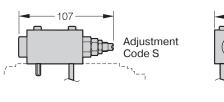




Warning: Risk of damaging bolt holes! Prior design series will need UNC bolts for pumps with threadcode "3".



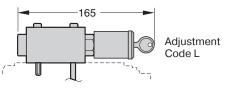
PVAC1P*



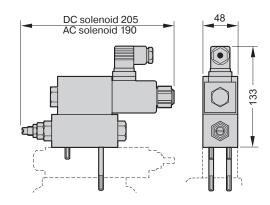


45

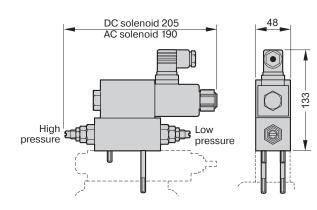
40



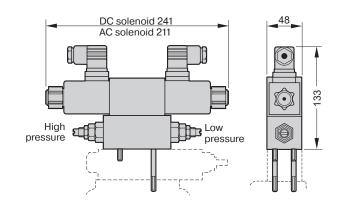
PVAC1E*



PVAC2P*



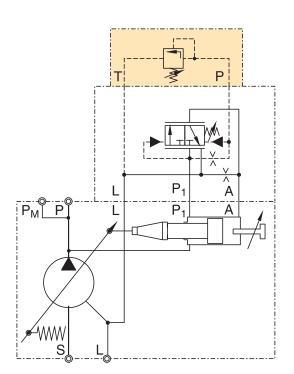
PVAC2M*/PVAC2E*

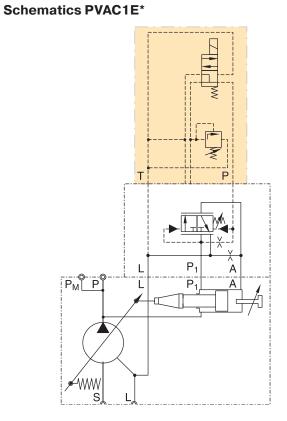


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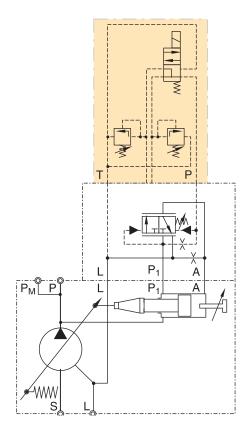


Schematics PVAC1P*

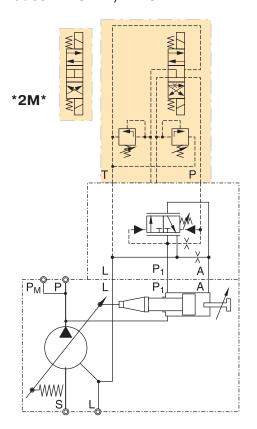




Schematics PVAC2P*



Schematics PVAC2M*/PVAC2E*



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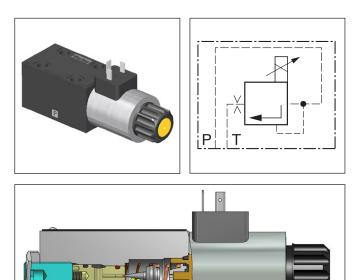


Proportional pressure relief valve PVACRE*

Function

When the pressure in port P exceeds the pressure setting at the solenoid, the poppet opens to port T and limits the pressure in port P to the adjusted level.

The optimum performance can be achieved in combination with the digital amplifier module PCD00A-400 (see catalogue HY11-3500 for reference).



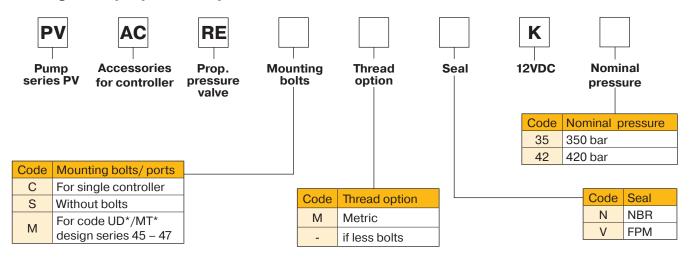
A T

Technical data

General		
Nominal size		DIN NG06 / CETOP03 / NFPA D03
Mounting position		as desired, horizontal mounting preferred
Ambient temperature	[°C]	-20 +70
Weight	[U] [kg]	
	[ĸy]	1.0
Hydraulic		
Max. operating pressure	[bar]	
Pressure stages	[bar]	350, 420
Fluid		Hydraulic oil as per DIN 51524 525
Viscosity, recommended	[cSt]/ [mm ² /s]	3080
permitted	[cSt]/ [mm ² /s]	
Fluid temperature	[°C]	-20+60
Filtration		ISO 4406 (1999), 18/16/13
Linearity	[%]	±4
Repeatability	[%]	±2
Hysteresis	[%]	±4.5 of p _{max}
Electrical		
Duty ratio	[%]	100 ED
Protection class		IP 65 in accordance with EN 60529 (plugged and mounted)
Nominal voltage	[V]	12 (2.2 A for nominal pressure)
Coil resistance	[Ohm]	4.4 at 20°C
Solenoid connection		Connector as per EN 175301-803
Power amplifier, recommended		PCD00A-400 (open loop – NO sensor),
		PWDXXA-400 (closed loop – with pressure sensor)



Ordering code proportional pressure relief valve

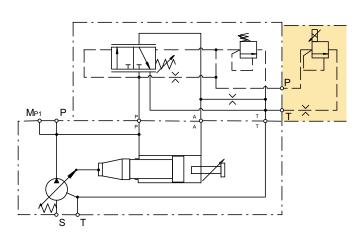


Warning:

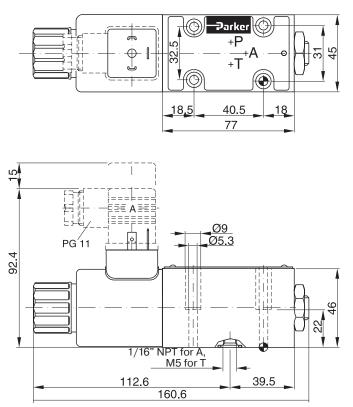
Risk of damaging bolt holes! Prior design series will need UNC bolts for pumps with threadcode "3".

Schematic PVACRE*

Example for PVACRE* mounted

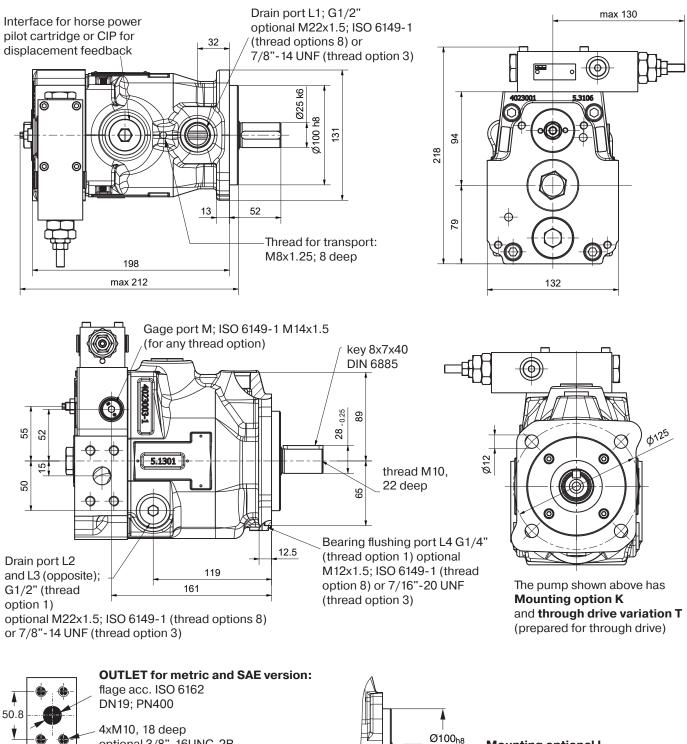


Dimensions PVACRE*

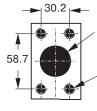




PV016-028, metric version

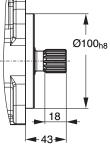


optional 3/8"-16UNC-2B (thread options 3)



INLET for metric and SAE version: flage acc. ISO 6162 DN32; PN250

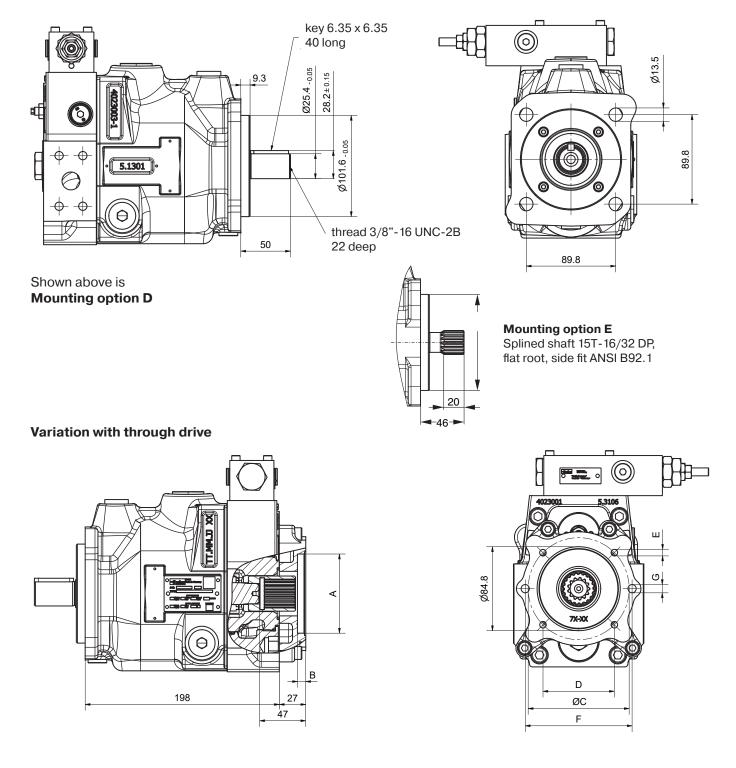
4xM10, 18 deep optional 7/16"-14UNC-2B (thread options 3)



Mounting optional L splined shaft W25x1.5x15x8f DIN 5480

Shown is a clockwise rotating pump with standard pressure compensator. Counter clockwise rotating pumps have inlet, outlet and gage port reversed.

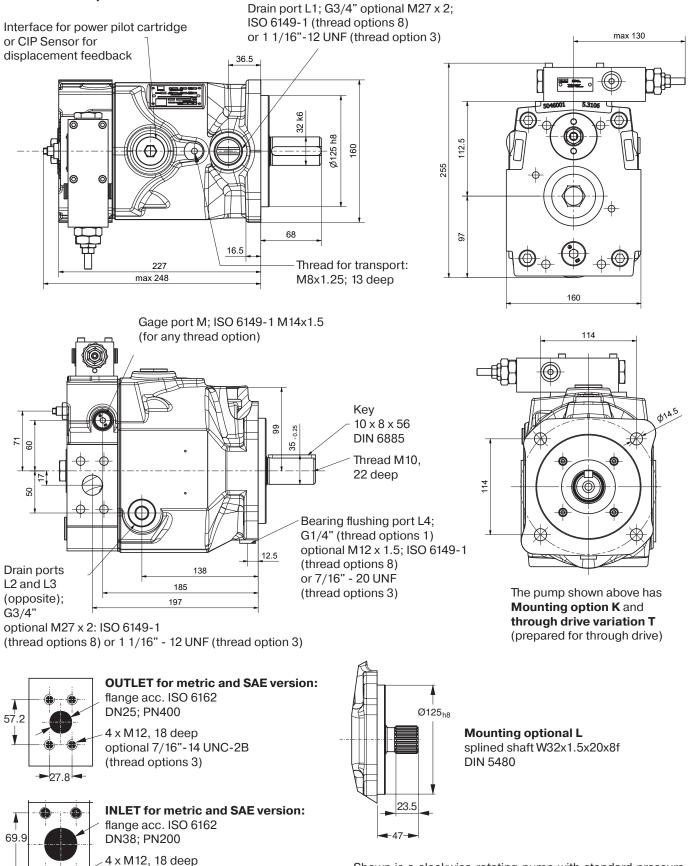
PV016-028, SAE version



Thr	Through drive adaptors are available with the following dimensions											
Drawing Dimension Through drive option	A	В	С	D	E	F	G	Remark				
А	82.55	8	-	-	-	106	M10	SAE A 2-Bolt				
В	101.6	10.5	127	89.8	M12	-	-	SAE B 4-Bolt				
J	100	10.5	125	88.4	M10	-	-	4-Bolt				







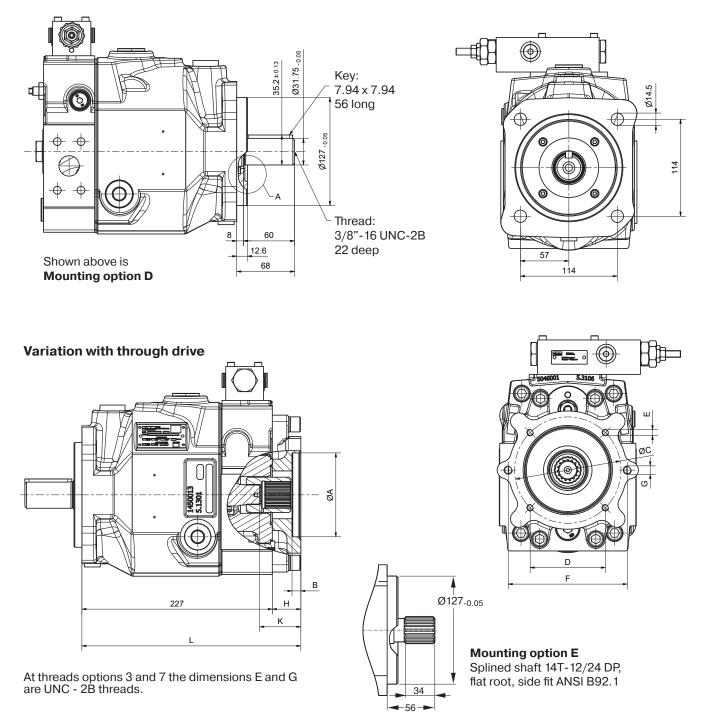
Shown is a clockwise rotating pump with standard pressure compensator. Counter clockwise rotating pumps have inlet, outlet and gage port reversed.

Parker

optional 1/2"-13 UNC-2B

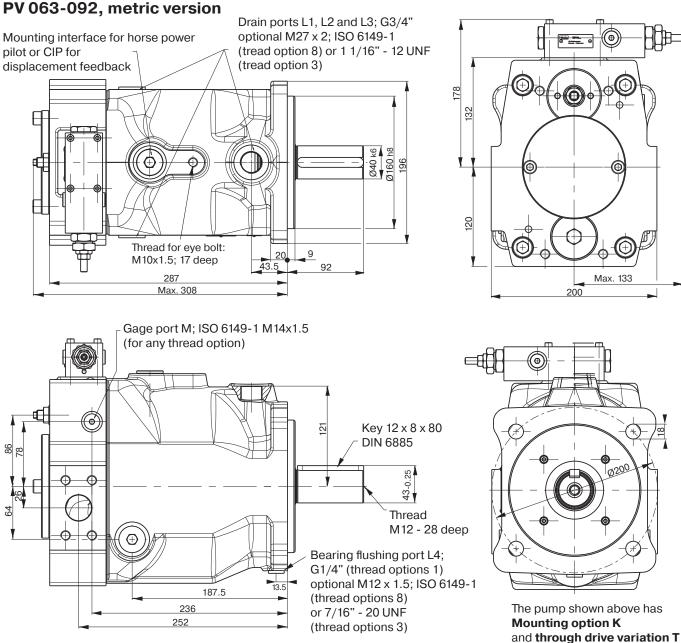
(thread options 3)

PV032-046, SAE version

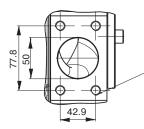


Th	Through drive adaptors are available with the following dimensions												
Drawing Dimension Through drive option	А	В	С	D	E	F	G	Н	к	L	Remark		
A	82.55	8	-	-	-	106	M10	34	48	261	SAE A 2-Bolt		
В	101.6	11	127	89.8	M12	146	M12	34	48	261	SAE B 2/4-Bolt		
С	127	13.5	162	114.6	M12	-	-	49	63	276	SAE C 4-Bolt		
J	100	10.5	125	88.4	M10	140	M12	34	48	261	2/4-Bolt		
К	125	10.5	160	113.1	M12	-	-	34	48	261	4-Bolt		





and through drive variation 1 (prepared for through drive)



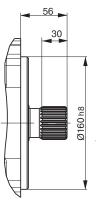
INLET for metric and SAE version: flange according ISO 6162

DN 51; PN 200 bar

4 x M12, 20 deep optional 1/2" - 13 UNC - 2B (thread options 3)

OUTLET for metric and SAE version: flange according ISO 6162 DN 32; PN 400 bar

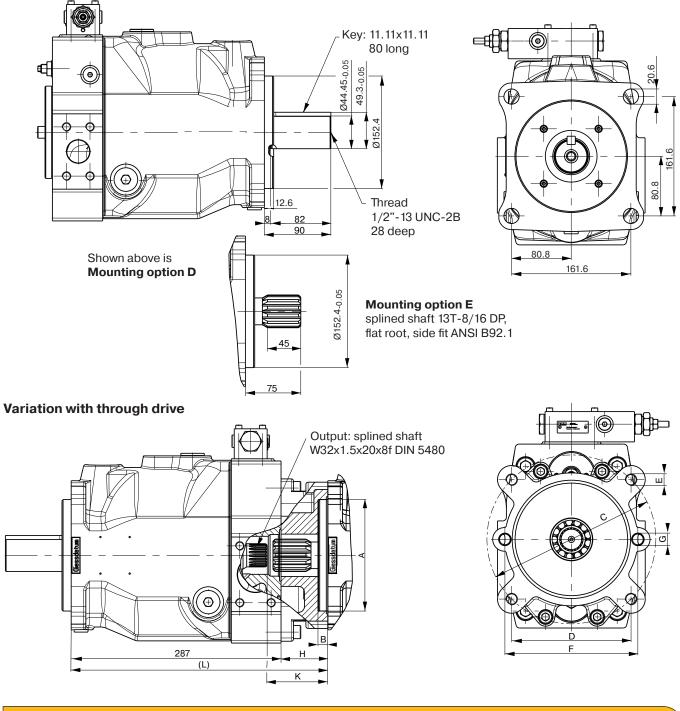
4 x M12, 20 deep optional 1/2" - 13 UNC - 2B (thread options 3) or 4 x M14, 20 deep (thread options 4)



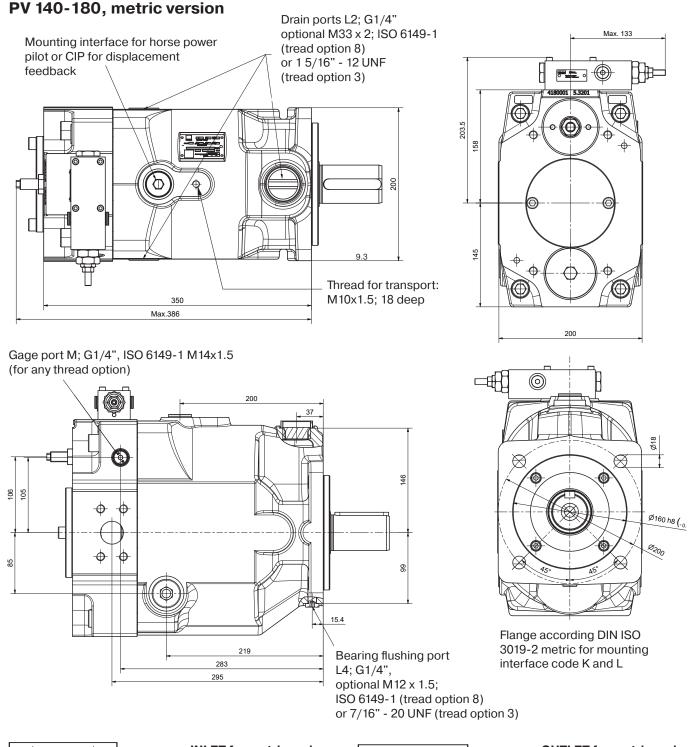
Mounting option L, splined shaft W40 x 1.5 x 25 x 8f DIN 5480

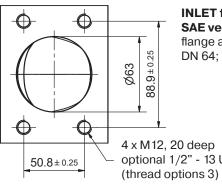
Shown is a clockwise rotating pump with standard pressure compensator. Counter clockwise rotating pumps have inlet, outlet and gage port reversed.

PV 063-092 SAE Version



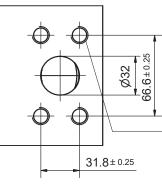
TI	Through drive adaptors are available with the following dimensions												
Drawing Dimension Through drive option		В	С	D	E	F	G	Н	К	L	Remark		
A	82.55	8	-	-	-	106	M10	39	58	326	SAE A 2-Bolt		
В	101.6	11	127	89.8	M12	146	M12	39	58	326	SAE B 2/4-Bolt		
С	127	13.5	162	114.6	M12	181	M16	39	58	326	SAE C 2/4-Bolt		
D	152.4	13.5	228.5	161.6	M16	-	-	64	83	351	SAE D 4-Bolt		
J	100	10.5	125	88.4	M10	140	M12	39	58	326	2/4-Bolt		
К	125	10.5	160	113.1	M12	180	M16	39	58	326	2/4-Bolt		
L	160	13.5	200	141.4	M16	-	-	39	58	326	4-Bolt		





INLET for metric and SAE version: flange according ISO 6162 DN 64; PN 160 bar

optional 1/2" - 13 UNC - 2B



OUTLET for metric and SAE version: flange according ISO 6162

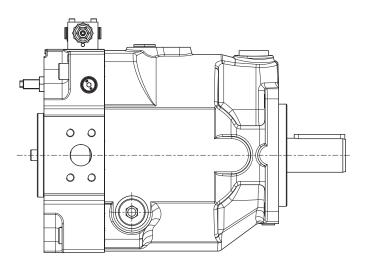
DN 32; PN 400 bar

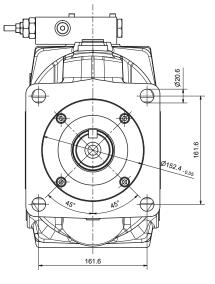
4 x M12, 20 deep optional 1/2" - 13 UNC - 2B (thread options 3) or 4 x M14, 22 deep (thread options 4)

PV 140-180 SAE Version

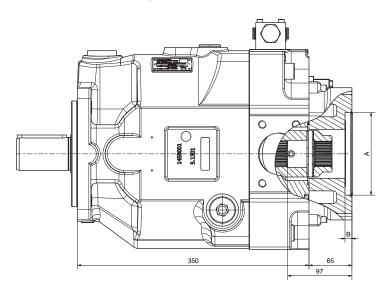
Flange according DIN ISO 3019-1 SAE for mounting interface code D, E, F and G

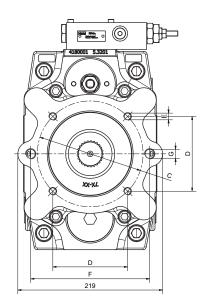
Shown are clockwise rotating pumps. Counter clockwise rotating pumps have inlet, outlet and gage port reversed.





Variation with through drive



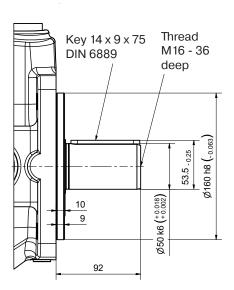


Thro	Through drive adaptors are available with the following dimensions												
Drawing Dimension Through drive option	А	В	С	D	E	F	G	Remark					
A	82.55	8	-	-	-	106	M10	SAE A 2-Bolt					
В	101.6	11	127	89.8	M12	146	M12	SAE B 2/4-Bolt					
С	127	13.5	162	114.6	M12	181	M16	SAE C 2/4-Bolt					
D	152.4	13.5	228.5	161.6	M16	-	-	SAE D 4-Bolt					
J	100	10.5	125	88.4	M10	140	M12	2/4-Bolt					
К	125	10.5	160	113.1	M12	180	M16	2/4-Bolt					
L	160	13.5	200	141.4	M16	-	-	4-Bolt					

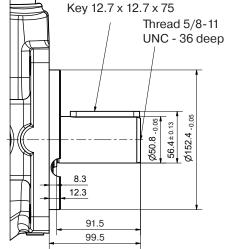


PV 140-180 Mounting options

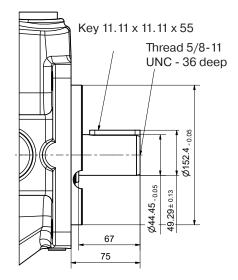
Mounting option K shaft keyed metric



Mounting option D shaft keyed SAE

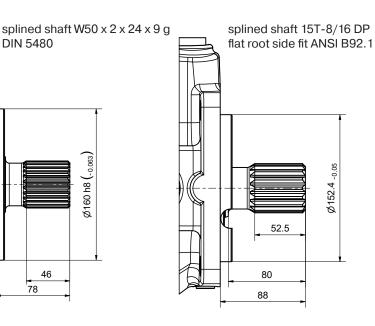


Mounting option F shaft keyed SAE

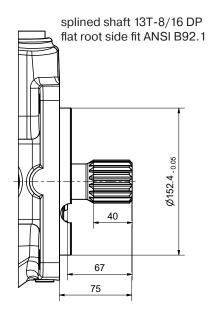


Mounting option L shaft splined metric

Mounting option E shaft splined SAE



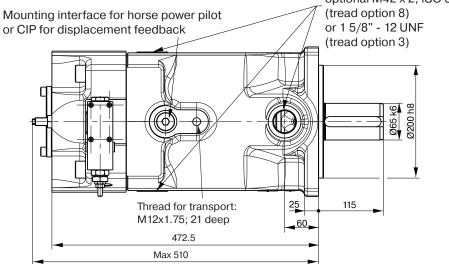
Mounting option G shaft splined SAE

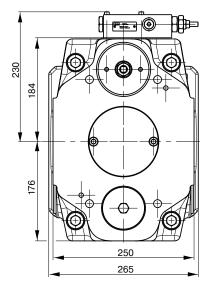




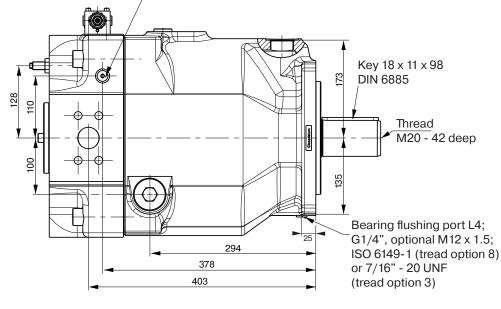
PV 270, metric version

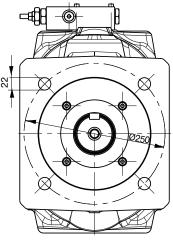




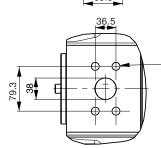


Gage port M; G1/4", ISO 6149-1 M14x1.5 (for any thread option)





The pump shown above has **Mounting option K** and **through drive variation T** (prepared for through drive)

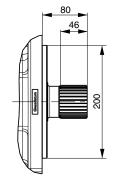


INLET for metric and SAE version: flange according ISO 6162 DN 89; PN 35 bar

4 x M16, 30 deep optional 5/8" - 11 UNC - 2B (thread options 3)

OUTLET for metric and SAE version:

flange according ISO 6162 DN 38; PN 400 bar 4 x M16, 30 deep optional 5/8" - 11 UNC - 2B (thread options 3)

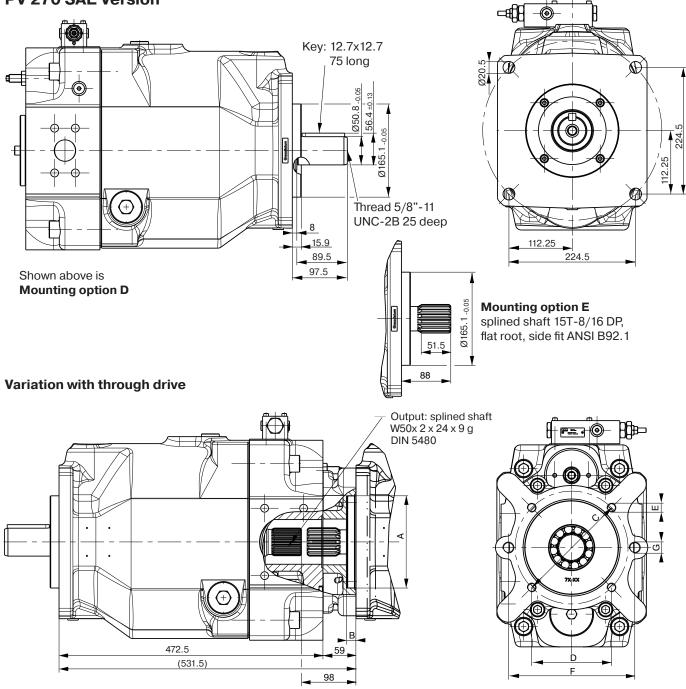


Mounting option L, splined shaft W60 x 2 x 28 x 9g DIN 5480

Shown is a clockwise rotating pump with standard pressure control. Counter clockwise rotating pump have inlet, outlet and gage port reversed.

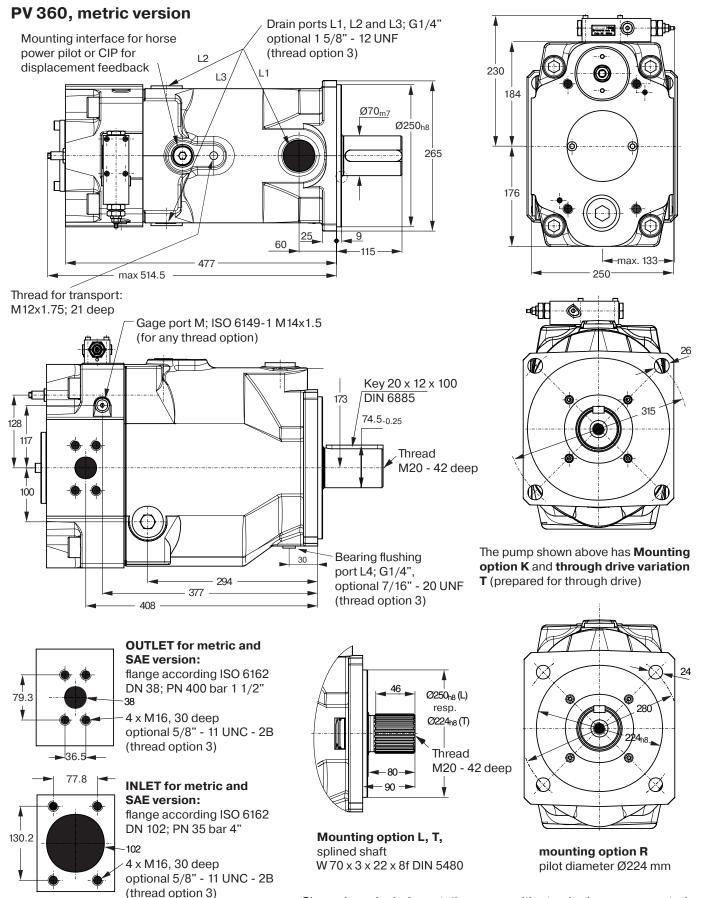


PV 270 SAE Version

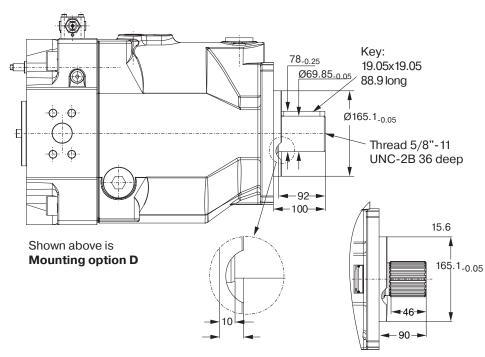


Th	Through drive adaptors are available with the following dimensions												
Drawing Dimension Through drive option		В	С	D	E	F	G	Remark					
A	82.55	8	-	-	-	106	M10	SAE A 2-Bolt					
В	101.6	11	127	89.8	M12	146	M12	SAE B 2/4-Bolt					
С	127	13.5	162	114.6	M12	181	M16	SAE C 2/4-Bolt					
D	152.4	13.5	228.5	161.6	M16	229	M16	SAE D 2/4-Bolt					
E	165.1	17	317.5	224.5	M20	-	-	SAE E 4-Bolt					
J	100	10.5	125	88.4	M10	140	M12	2/4-Bolt					
К	125	10.5	160	113.1	M12	180	M16	2/4-Bolt					
L	160	13.5	200	141.4	M16	224	M20	2/4-Bolt					
М	200	13.5	250	176.8	M20	-	-	4-Bolt					

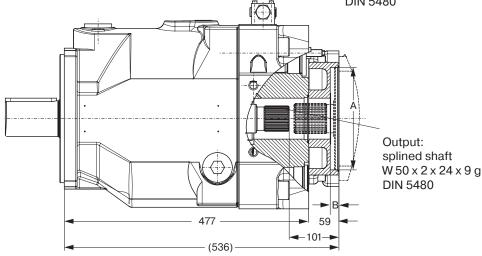




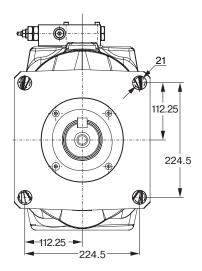
Shown is a clockwise rotating pump with standard pressure control. Counter clockwise rotating pump have inlet, outlet and gage port reversed. **PV 360 SAE Version**



Variation with through drive

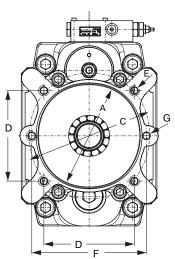


Mounting option E splined shaft W 70x3x22x8f, DIN 5480



Note:

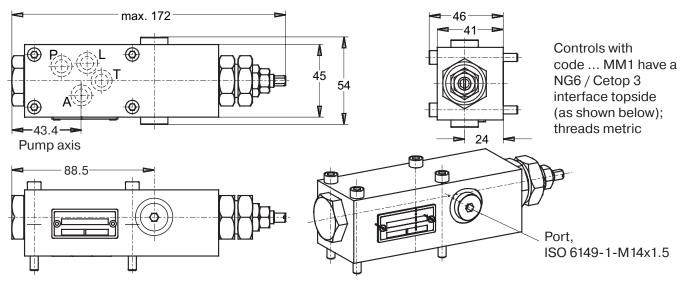
The dimensions shown conform to ISO 3019/1 the actual hole dimensions conform to ISO 3019/2 (pitch Ø315, hole Ø26, see previous page) and cover ISO 3019/1 dimensions as well. Use washers when assembling pump.



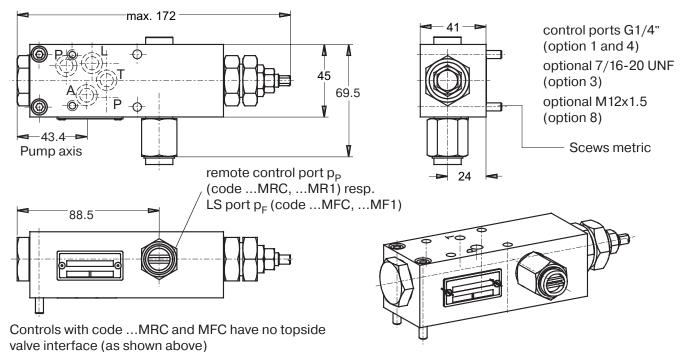
т	hrough dri	ive adapto	rs are avai	lable with	the followi	ng dimens	ions	
Drawing Dimension Through drive option	A	В	С	D	E	F	G	Remark
А	82.55	8	-	-	-	106	M10	SAE A 2-Bolt
В	101.6	11	127	89.8	M12	146	M12	SAE B 2/4-Bolt
С	127	13.5	162	114.6	M12	181	M16	SAE C 2/4-Bolt
D	152.4	13.5	228.5	161.6	M16	229	M16	SAE D 2/4-Bolt
E	165.1	17	317.5	224.5	M20	-	-	SAE E 4-Bolt
J	100	10.5	125	88.4	M10	140	M12	2/4-Bolt
К	125	10.5	160	113.1	M12	180	M16	2/4-Bolt
L	160	13.5	200	141.4	M16	224	M20	2/4-Bolt
М	200	13.5	250	176.8	M20	-	-	4-Bolt



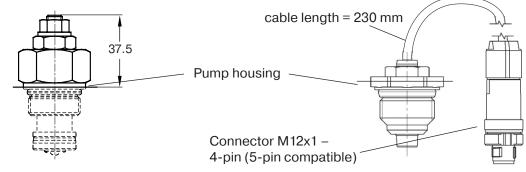
Dimensions standard pressure control, code ... MMC



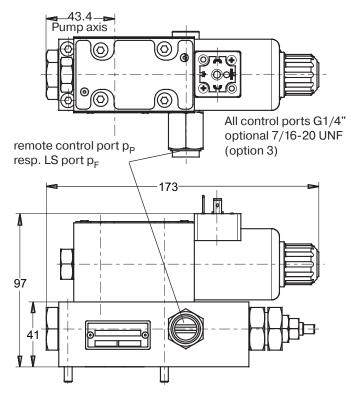
Dimensions remote pressure and load sensing control, codes ... MR1, ... MF1



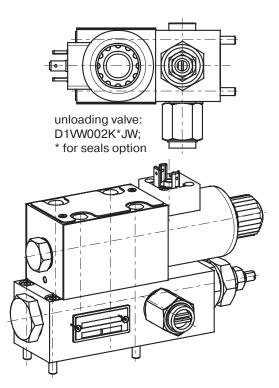
Dimensions horse power pilot cartridge, displacement sensor (<u>C</u>ontactless <u>Inductive P</u>osition)





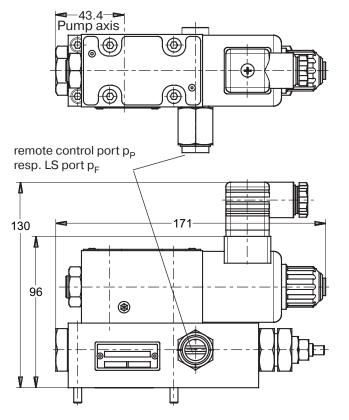


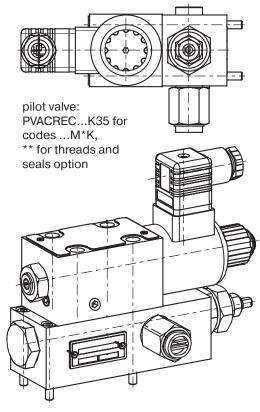
Dimensions for controls with unloading valve, codes ... M*W



Shown in version MRW/MFW, version MMW has no remote control port.

Dimensions for controls with proportional pressure pilot valve, codes $\dots M^*K$



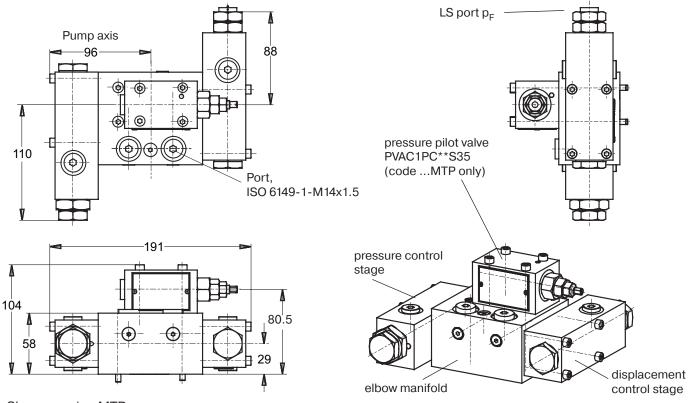


Shown in version MRK/MFK, version MMK has no remote control port. Dimensions for horse power compensator *L* and *C* are identical to MM* respectively MF*.



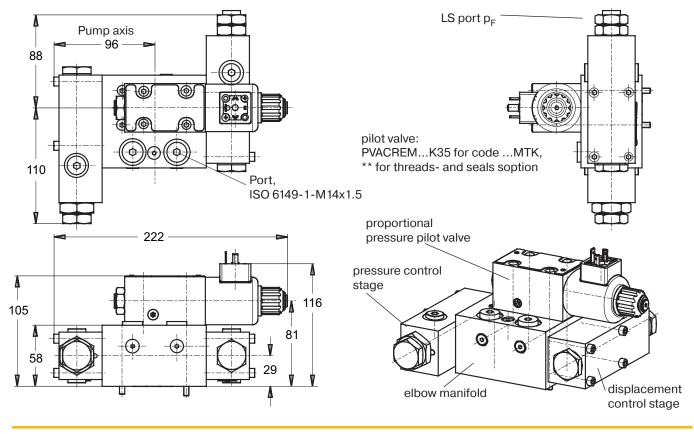
Dimensions two spool load sensing control, code ...MT1, ...MTP

All connecting scews metric

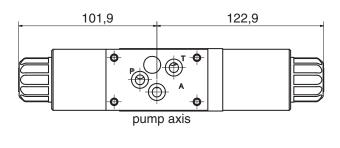


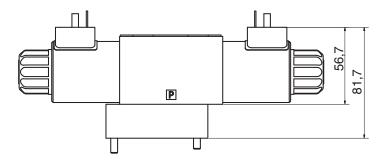
Shown version MTP

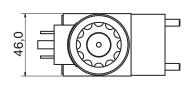
Dimensions two spool load sensing control with proportional pressure pilot valve, code ...MTK – All connecting scews metric

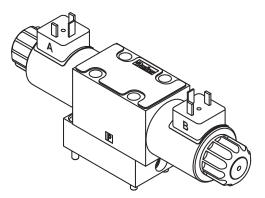


Dimensions proportional displacement control, code ... FDV - All connecting scews metric



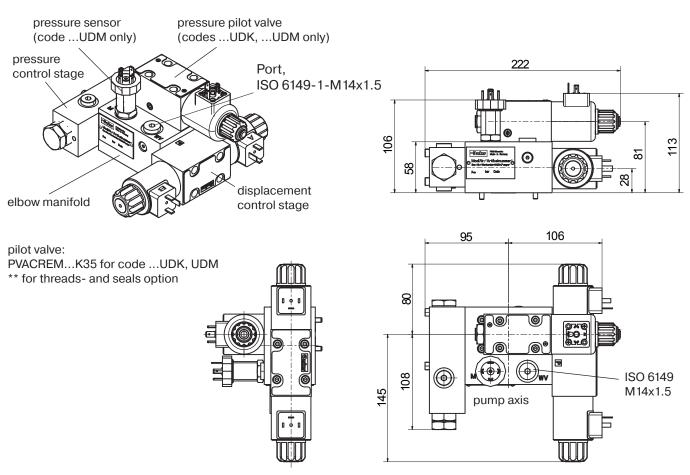






Dimensions proportional p/Q-control, codes ... UDR, ... UDK, ... UDM

All connecting scews metric





Features

- · Digital control circuit
- Covers all displacements
- · Covers all available functions (pressure, displacement, power)
- Predefined parameter sets (Plug & Play)
- Connection via USB cable (USB-A/USB-B)
- Ramp time up to 60 seconds
- · Compliant to the relevant european EMC specifications
- · Offline editing of parameter sets
- Error diagnosis
- · Easy hands on control tuning due to online monitoring of PID gains
- All settings (ramps, MIN/MAX, control parameters) can be stored digitally and recalled from a PC to duplicate settings to other modules



Technical data

Mounting style		Snap-on mounting for EN50022 rail
Body material		Polycarbonate
Inflammation class		V2V0 acc. UL 94
Mounting position		any
Env. temperature range	[°C]	-20+55
Protection class		IP 20 acc. DIN 40 050
Weight	[g]	260
Duty ratio	[%]	100
Supply voltage	[V]	1830 VDC, ripple <5 % eff.
Rush in current	[A]	22 for 0.2 ms
Current consumption	[A]	< 4 for p/Q control ; < 2 for Q-control
Resolution Input Command	[%]	0.025 (power 0.1)
Interface		USB-Typ B
EMC		EN 50 081-2, EN 50 082-2
Connctors		Screw terminals 0.22.5 mm ² , plug in style
Cables	[mm ²]	
		Sensor and command signals; 0.5 mm ² (AWG20) overall braid shield
Max. cable length	[m]	50

For programming the module via PC an interface cable is needed, please order part number PQDXXA-ZXX-KABEL separately.

Ordering code

Programming software

common windows systems.





series PV



downward compatible * Z00

Digital control module for p/Q frame sizes control

The programming of the p/Q control module is done in

an easy to learn mode. To select the pump model and

size and to set the control parameters the program

ProPVplus must be started. The program runs under

Latest software available at: www.parker.com/pmde







Features

- Display and documentation of parameter sets
- · Save and reload of optimized parameter sets
- · Offers oscilloscope function for easy performance evaluation and optimization
- · Parameter sets for all PVplus pumps are pre-installed in the modules

Features

- · Control, monitor and parameter setting via Profinet ® interface
- Covers all displacements and controls (pressure, displacement, power)
- Quick and easy integration with available GSDML and predefined and online available function blocks for I/ Os as well as parametrization
- · Full integration into overlaying machine control (PLC + HMI) Process parameter, Static Parameter, Conditions
- Predefined data sets for Plug&Play commissioning
- · Quick and easy wiring with Push in contact blocks
- Switch function with two RJ45 ports
- Alternative Connection via USB cable (USB-A/USB-B)
- · Compatible to the relevant european EMC specification
- Certified by Profibus User Organisation
- Easy error diagnosis

Technical data

Mounting style		Snap-on mounting for EN50022
Body material		Polyamide PA6.6
Inflammation class		V0 acc. UL 94
Mounting position		any
Env. temperature range	[°C]	-20+55
Protection class		IP 20 acc. DIN 40 050
Weight	[g]	260
Duty ratio	[%]	100
Supply voltage	[V]	1830 VDC, ripple <5 % eff.
Rush in current	[A]	22 for 0.2 ms
Current consumption	[A]	< 4 for p/Q control ; < 2 for Q-control
Resolution Input Command	[%]	0.025 (power 0.1)
Interface		2 x RJ45, USB-B
EMC		EN61000-6-2: 2005 (Immunity), EN61000-6-3: 2007 +A1: 2010 (Emission)
Connectors		Push in terminals 0.22.5 mm ² , plug in style
Cables	[mm ²]	Supply and solenoid cables; 1.5 mm ² (AWG16) overall braid shield.
		Sensor and command signals; 0.5 mm ² (AWG20) overall braid shield
Max. cable length	[m]	50

Further information at bulletin MSG30-3256-INST/UK

Ordering code

Programming software

common windows systems.







Z10	
Option	

Digital control module for p/Q control

The programming of the p/Q control module is done

in an easy to learn mode. To select the pump model

and size and to set the control parameters the program

ProPVplus must be started. The program runs under

Latest software available at: www.parker.com/pmde



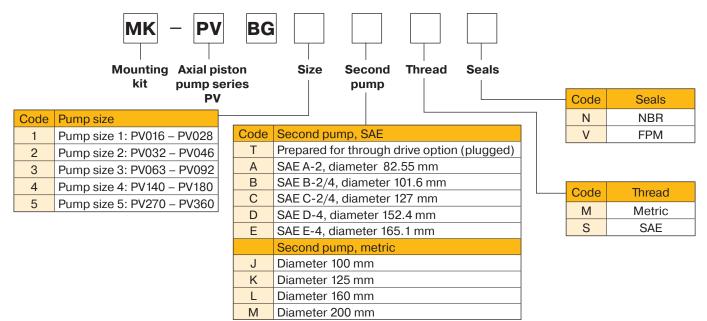
Features

- · Display and documentation of parameter sets
- · Save and reload of optimized parameter sets
- Offers oscilloscope function for easy performance evaluation and optimization
- · Parameter sets for all PVplus pumps are pre-installed in the modules



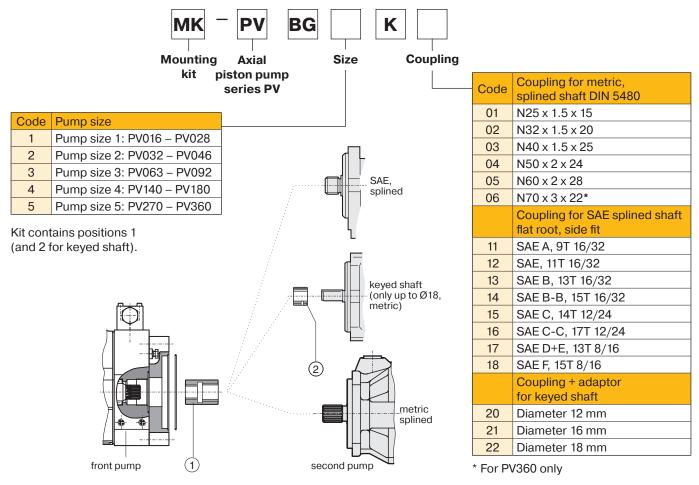


Mounting kits for multiple pumps, for second pump option



Kit contains positions 30, 69, 84, 85 and 87, see spare part list

Mounting kits for multiple pumps, couplings

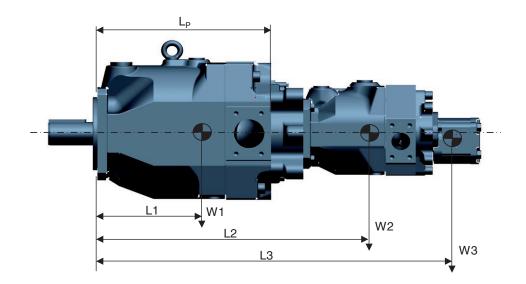


Availability of through drive flange and coupling please check with ordering code options per each pump size, starting at page 6



Multiple Pump Combinations – Maximum Moment

Combinations of multiple pumps might require additional pump support to avoid high stress on the front mounting flange. Combinations of two PVplus pumps in the same frame size generally do not need additional support in an industrial application. For combinations of more pumps support is required. In case of combinations of a PVplus pump with another type of pump it is recommended to calculate the moment for the combination and compare with the maximum moment in table 1 below.



Moment M = (L1*W1 + L2*W2 + L3*W3 +...)

Note: If the calculated moment M exceed the maximum moment in table 1 below, additional pump support is needed

Table 1: Maximum Moment and Pump Dimensions

		PV016-PV028	PV032-PV046	PV063-PV092	PV140-PV180	PV270	PV360
Maximum moment 1)	[Nm]	81	151	401	591	1686	1686
Weight W	[N]	186	294	589	883	1687	1766
Distance L1	[mm to C/G]	106	119	178	184	234	238
Distance Lp	[mm]	197.5	227	287	350	472.5	477

¹⁾ at dynamic weight acceleration $10g = 98.1 \text{ m/sec}^2$

Table 2 Through Drive Adapter Plate Thickness [mm]

Adapter option ²⁾	PV016-PV028	PV032-PV046	PV063-PV092	PV140-PV180	PV270	PV360
A	27	34	39	65	59	59
В	27	34	39	65	59	59
С	-	49	39	65	59	59
D	-	-	64	65	59	59
E	-	-	-	-	59	59
G	27	34	39	-	-	-
J	27	34	39	65	59	59
К	-	34	39	65	59	59
L	-	-	39	65	59	59
М	-	-	-	-	59	59

²⁾ See page 6 to 17 for reference per each frame size.



Maximum allowed transferable torque FRONT								
Shaft	Shaft	Transferable torque at FRONT shaft end. [Nm]						
code	type	PV016-028	PV032- 046	PV063- 092	PV140-180	PV270	PV360	
D	SAE - Key	300	650	1850	2150	2150	4750	
E	SAE - Spline	320	630	1700	2750	2800	8100*	
F	SAE - Key				1200			
G	SAE - Spline				1700			
R	Metric - Key						3750	
т	Metric - Spline						8100	
к	Metric - Key	280	640	1200	1550	3300	3750	
L	Metric - Spline	320	720	1500	3050	5750	8100	
Maximum allowed transferable torque REAR								
Max. torque transmission cap. for rear mounted pump		350	520	1100	1550	3150	3250	

* DIN5480 splined

Important notice:

The max. allowable torque of the individual shaft must not be exceeded. For 2-pump combinations there is no problem because PV series offers 100 % through torque. For 3-pump combinations (and more) the limit torque could be reached or exceeded.

Therefore it is necessary to calculate the resulting input as well as through drive torque.





Change History with 47 design:

- New displacement feedback sensor (CIP) is introduced. Previously used LVDT is not available with new design series any longer.
- Attention: All bolts/threads for controls, accessories and throughdrives unified to metric.
- Attention: Measuring-, external pilot-, remoteports all unified to metric M14x1.5. Remote adapters towards G1/4 and 7/16 20 UNF still available and included with remote/LS-control
- Airbleed-valves and respective cavities fully removed.
- Eye bolts removed from delivery content. Thread in casting remains and may be used for lifting purpose



WARNING - USER RESPONSIBILITY

FAILURE OR IMPROPER SELECTION OR IMPROPER USE OF THE PRODUCTS DESCRIBED HEREIN OR RELATED ITEMS CAN CAUSE DEATH, PERSONAL INJURY AND PROPERTY DAMAGE.

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